



# ON THE APPLICATION OF OPTIMIZATION METHODS FOR SECURED MULTIPARTY COMPUTATIONS

**C. Weeraddana\***, G. Athanasiou\*, M. Jakobsson\*,  
C. Fischione\*, and J. S. Baras\*\*

\*KTH Royal Institute of Technology, Stockholm, Sweden

\*\*University of Maryland, MD, USA

{chatw, georgia, mjakobss, carlofi}@kth.se; baras@umd.edu

ACCESS ISS 18.09.13



# Motivation – Why Privacy/Security ?

- social networks



# Motivation – Why Privacy/Security ?

- social networks
- healthcare data



# Motivation – Why Privacy/Security ?

- social networks
- healthcare data
- e-commerce



Protect  
Patient  
Information



# Motivation – Why Privacy/Security ?

- social networks



- healthcare data

Protect  
Patient  
Information



- e-commerce



- banks, and government services



# Motivation – Why Privacy/Security ?

- real world:
  - different parties, such as persons and organizations **always interact**
  - they collaborate for mutual benefits

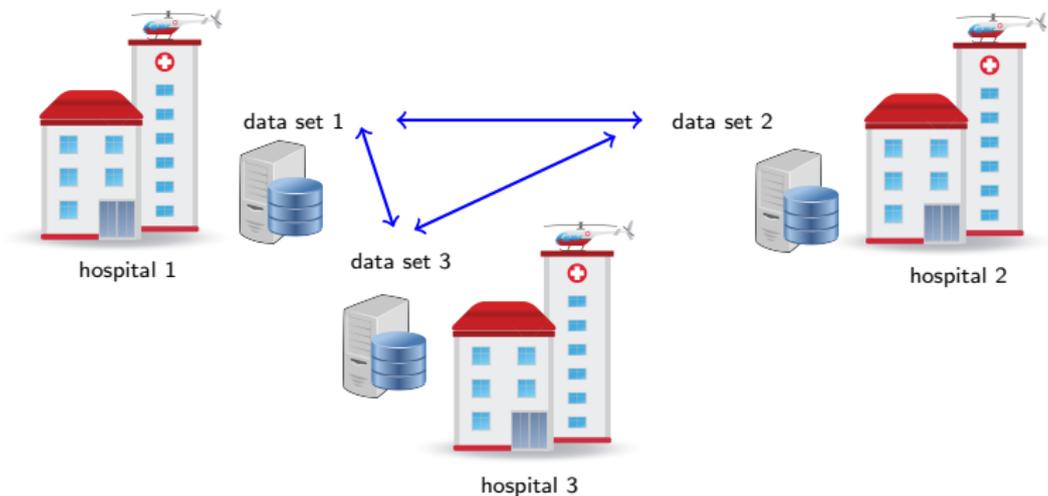
# Motivation – Why Privacy/Security ?

- real world:
  - different parties, such as persons and organizations **always interact**
  - they collaborate for mutual benefits
  
- collaboration is more appealing **if** security/privacy is guaranteed

# Real World

- **example 1**

- hospitals coordinate  $\Rightarrow$  inference for better diagnosis
- larger data sets  $\Rightarrow$  higher the accuracy of the inference
- **challenge:** neither of the data set should be revealed



# Real World

- **example 2**

- cloud customers outsource their problems to the cloud
- **challenge:** problem data shouldn't be revealed to the cloud



# Real World

- **example 3**

- secured e-voting systems
- **challenge:** neither of the vote should be revealed

candidate 1



candidate 2



X	X				X	X
		X	X	X		

vote 1

vote 2

.....

vote N

# Secured Multiparty Computation

- solve, **in a secured manner**, the  $n$ -party problem of the form:

$$f(\mathbf{A}_1, \dots, \mathbf{A}_n) = \inf_{\mathbf{x} \in \{\mathbf{x} | \mathbf{g}(\mathbf{x}, \mathbf{A}_1, \dots, \mathbf{A}_n) \leq \mathbf{0}\}} f_0(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{A}_1, \dots, \mathbf{A}_n)$$

- $\mathbf{A}_i$  is the private data belonging to party  $i$
- $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$  is the decision variable
- $f_0(\cdot)$  is the global objective function
- $\mathbf{g}(\cdot)$  is the vector-valued constraint function
- $f(\cdot)$  is the desired optimal value

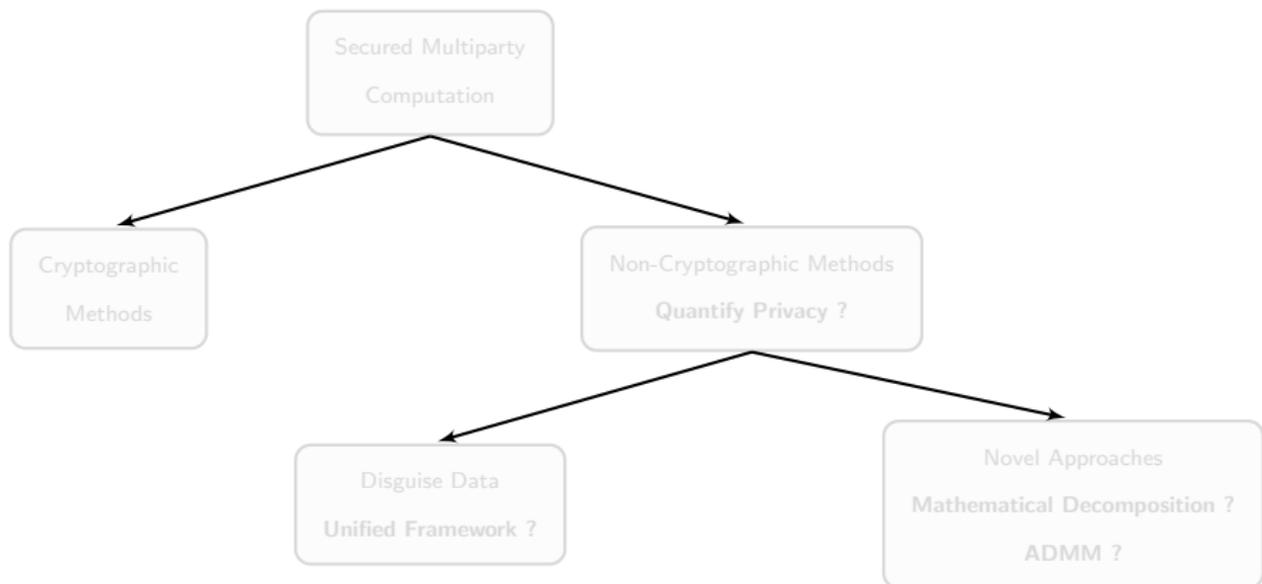
# Secured Multiparty Computation

- solve, **in a secured manner**, the  $n$ -party problem of the form:

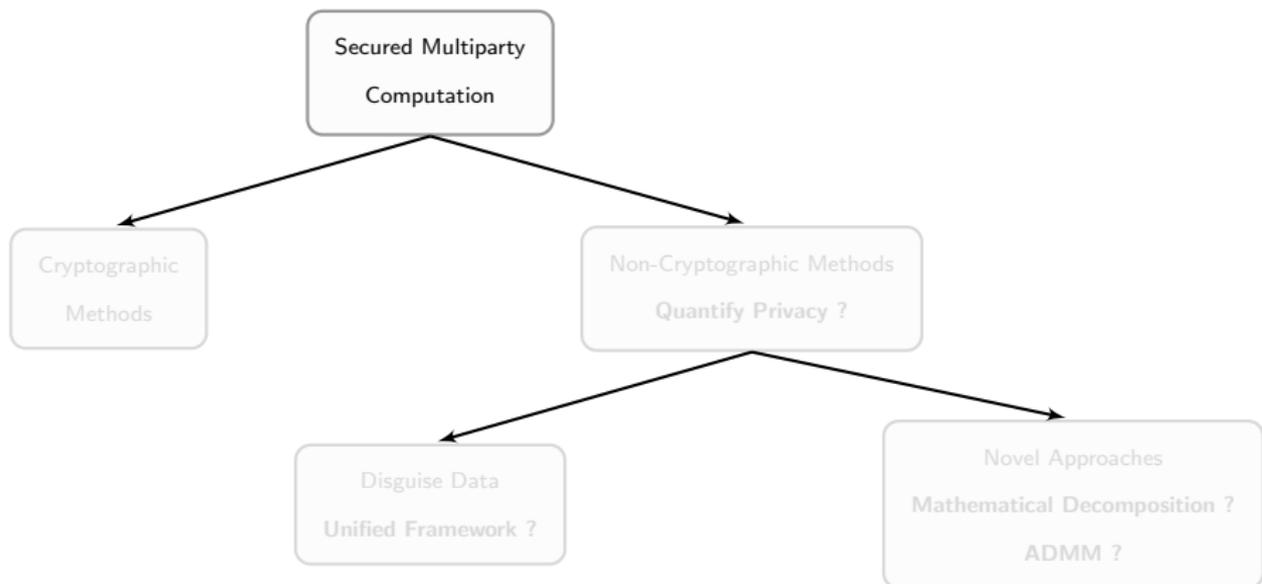
$$f(\mathbf{A}_1, \dots, \mathbf{A}_n) = \inf_{\mathbf{x} \in \{\mathbf{x} | \mathbf{g}(\mathbf{x}, \mathbf{A}_1, \dots, \mathbf{A}_n) \leq \mathbf{0}\}} f_0(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{A}_1, \dots, \mathbf{A}_n)$$

- $\mathbf{A}_i$  is the private data belonging to party  $i$
  - $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$  is the decision variable
  - $f_0(\cdot)$  is the global objective function
  - $\mathbf{g}(\cdot)$  is the vector-valued constraint function
  - $f(\cdot)$  is the desired optimal value
- 
- can we perform such computations with “acceptable” privacy guaranties ?

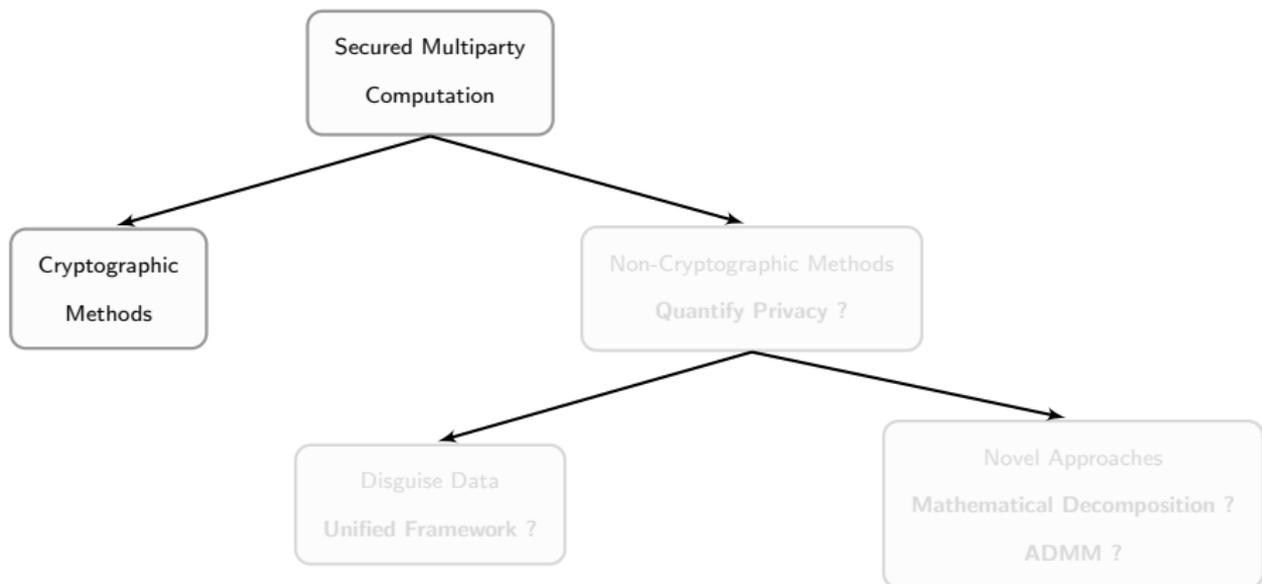
# Overview



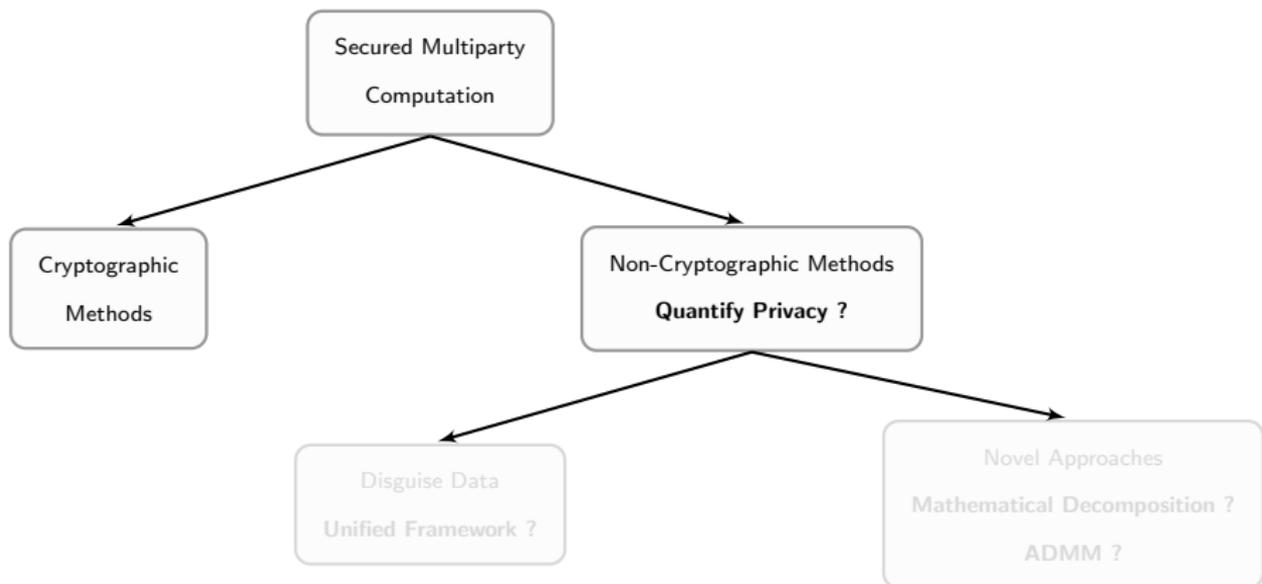
# Overview



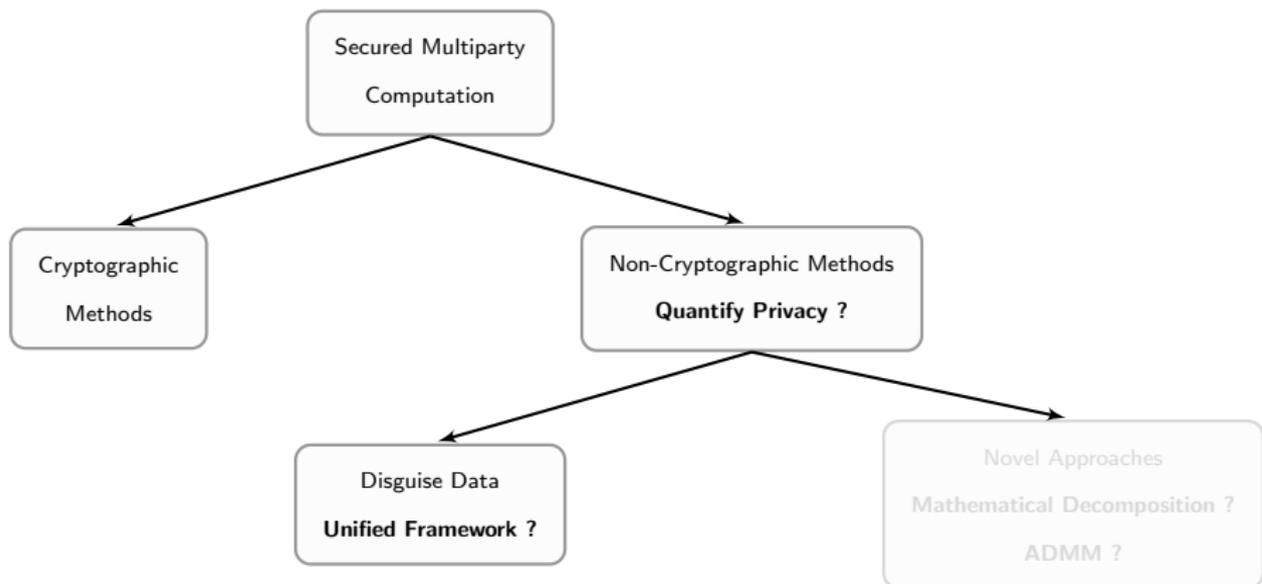
# Overview



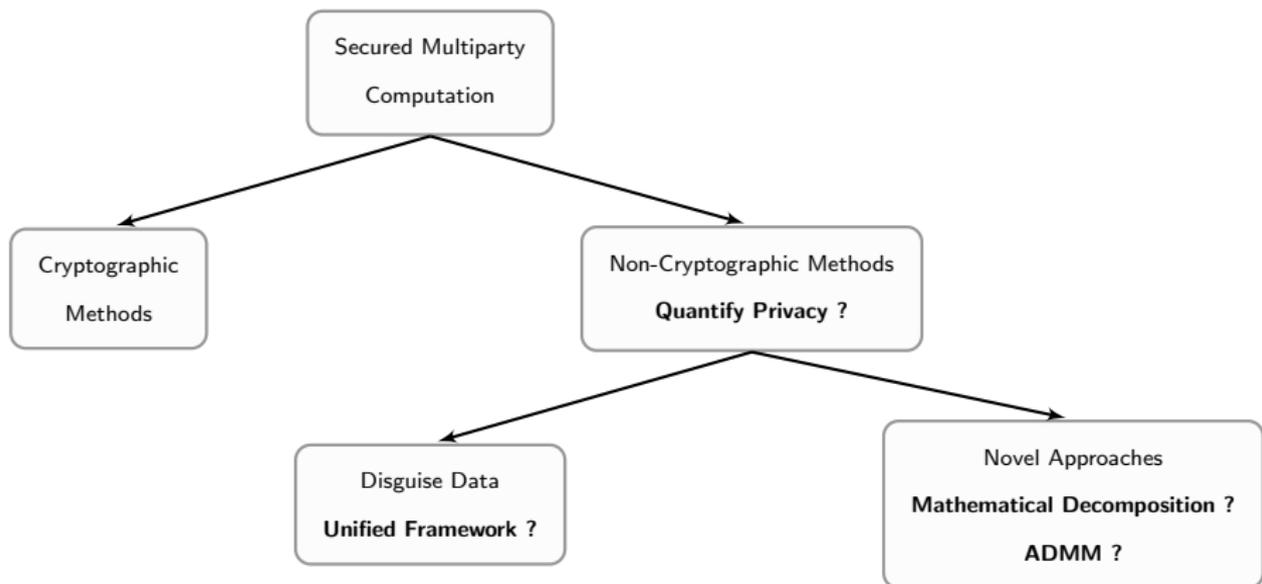
# Overview



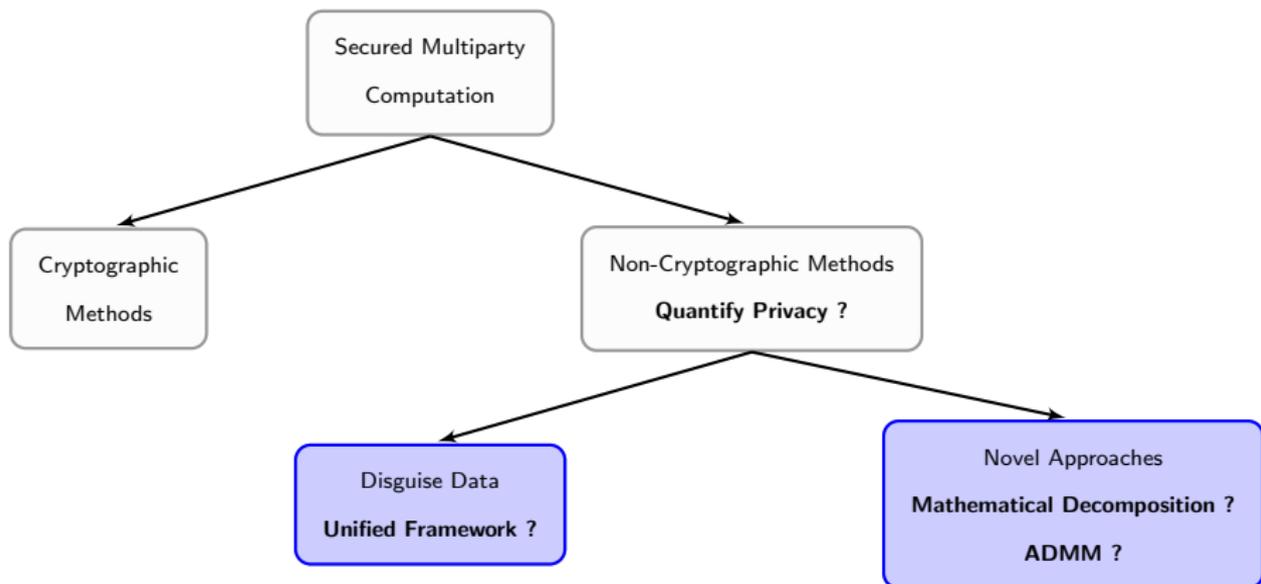
# Overview



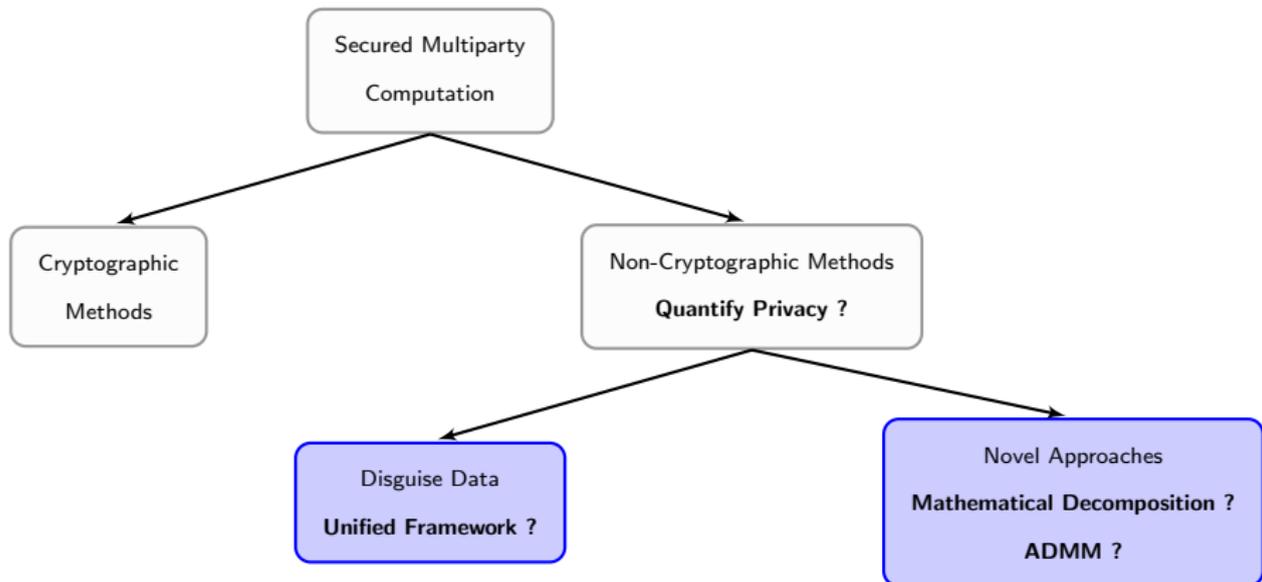
# Overview



# Overview



# Our Contributions



# Our Contributions

- **unified framework** for existing methods for disguising private data
  - absence of a systematic approach reduces the scope of applicability
  - unintended mistakes (e.g., [Du01, Vai09])
  - standard proof techniques for privacy guaranties.
- **decomposition methods, ADMM**
- **general definition** for privacy  $\Rightarrow$  quantify the privacy
- **a number of examples**
- **comparison:** efficiency, scalability, and many others
- for details, see [WAJ<sup>+</sup>13]

[WAJ<sup>+</sup>13] P. C. Weeraddana, G. Athanasiou, M. Jakobsson, C. Fischione, and J. S. Baras. Per-se privacy preserving distributed optimization



# General Formulation

we pose the design or decision making problem

$$\begin{aligned} & \text{minimize} && f_0(\mathbf{x}) \\ & \text{subject to} && f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, q \\ & && \mathbf{C}\mathbf{x} - \mathbf{d} = \mathbf{0} \end{aligned} \tag{1}$$

- optimization variable is  $\mathbf{x} \in \mathbb{R}^n$
- $f_i, i = 0, \dots, q$  are *convex*
- $\mathbf{C} \in \mathbb{R}^{p \times n}$  with  $\text{rank}(\mathbf{C}) = p$
- $\mathbf{d} \in \mathbb{R}^p$
  
- **we would like to solve the problem in a privacy preserving manner**

## Proposition (change of variables)

- $\phi : \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a function, with image covering the problem domain  $\mathcal{D}$
- change of variables:

$$\mathbf{x} = \phi(\mathbf{z}) . \quad (2)$$

- resulting problem:

$$\begin{array}{ll} \text{minimize} & f_0(\phi(\mathbf{z})) \\ \text{subject to} & f_i(\phi(\mathbf{z})) \leq 0, \quad i = 1, \dots, q \\ & \mathbf{C}\phi(\mathbf{z}) - \mathbf{d} = \mathbf{0} \end{array} \quad (3)$$

- $\mathbf{x}^*$  solves problem (1)  $\Rightarrow \mathbf{z}^* = \phi^{-1}(\mathbf{x}^*)$  solves problem (3)
- $\mathbf{z}^*$  solves problem (3)  $\Rightarrow \mathbf{x}^* = \phi(\mathbf{z}^*)$  solves problem (1)

## Proposition (change of variables)

- $\phi : \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a function, with image covering the problem domain  $\mathcal{D}$
- change of variables:

$$\mathbf{x} = \phi(\mathbf{z}) . \quad (2)$$

- resulting problem:

$$\begin{array}{ll} \text{minimize} & f_0(\phi(\mathbf{z})) \\ \text{subject to} & f_i(\phi(\mathbf{z})) \leq 0, \quad i = 1, \dots, q \\ & \mathbf{C}\phi(\mathbf{z}) - \mathbf{d} = \mathbf{0} \end{array} \quad (3)$$

- $\mathbf{x}^*$  solves problem (1)  $\Rightarrow \mathbf{z}^* = \phi^{-1}(\mathbf{x}^*)$  solves problem (3)
- $\mathbf{z}^*$  solves problem (3)  $\Rightarrow \mathbf{x}^* = \phi(\mathbf{z}^*)$  solves problem (1)

privacy is via the function compositions:

$$\hat{f}_i(\mathbf{z}) = f_i(\phi(\mathbf{z})) , \quad \text{dom} \hat{f}_i = \{\mathbf{z} \in \text{dom} \phi \mid \phi(\mathbf{z}) \in \text{dom} f_i\}$$

$$\hat{h}_i(\mathbf{z}) = \mathbf{C}\phi(\mathbf{z}) - \mathbf{d} , \quad \text{dom} \hat{h}_i = \{\mathbf{z} \in \text{dom} \phi \mid \phi(\mathbf{z}) \in \mathbb{R}^n\}$$



# Example of Change of Variables

- **original problem (big LP):**

$$\begin{aligned} & \text{minimize} && \mathbf{c}^\top \mathbf{x} \\ & \text{subject to} && \mathbf{A}\mathbf{x} \geq \mathbf{b} \end{aligned}$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
- private data:  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$

- **affine transformation:**  $\mathbf{x} = \phi(\mathbf{z}) = \mathbf{B}\mathbf{z} - \mathbf{a}$ ,  $\mathbf{B} \in \mathbb{R}^{n \times p}$ ,  
 $\text{rank}(\mathbf{B}) = n$ ,  $\mathbf{a} \in \mathbb{R}^n$ .

# Example of Change of Variables

- **original problem (big LP):**

$$\begin{aligned} & \text{minimize} && \mathbf{c}^T \mathbf{x} \\ & \text{subject to} && \mathbf{A} \mathbf{x} \geq \mathbf{b} \end{aligned}$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
- private data:  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$

- **affine transformation:**  $\mathbf{x} = \phi(\mathbf{z}) = \mathbf{B} \mathbf{z} - \mathbf{a}$ ,  $\mathbf{B} \in \mathbb{R}^{n \times p}$ ,  $\text{rank}(\mathbf{B}) = n$ ,  $\mathbf{a} \in \mathbb{R}^n$ .

- **equivalent problem (outsourced to the cloud):**

$$\begin{aligned} & \text{minimize} && \hat{\mathbf{c}}^T \mathbf{z} \\ & \text{subject to} && \hat{\mathbf{A}} \mathbf{z} \geq \hat{\mathbf{b}} \end{aligned}$$

- variable is  $\mathbf{z} \in \mathbb{R}^p$
- data:  $\hat{\mathbf{c}} = \mathbf{B}^T \mathbf{c} \in \mathbb{R}^p$ ,  $\hat{\mathbf{A}} = \mathbf{A} \mathbf{B} \in \mathbb{R}^{m \times p}$ ,  $\hat{\mathbf{b}} = \mathbf{b} - \mathbf{A} \mathbf{a} \in \mathbb{R}^m$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{aligned} & \text{minimize} && (1/K) \sum_{i=1}^K x_i \\ & \text{subject to} && x_i = a_i, i = 1, \dots, K \end{aligned}$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
- private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{aligned} & \text{minimize} && (1/K) \sum_{i=1}^K x_i \\ & \text{subject to} && x_i = a_i, i = 1, \dots, K \end{aligned}$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
  - private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$
- **affine transformation:**  $x_i = \phi_i(z_i) = z_i - \alpha_i, n = 1, \dots, K.$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{aligned} & \text{minimize} && (1/K) \sum_{i=1}^K x_i \\ & \text{subject to} && x_i = a_i, i = 1, \dots, K \end{aligned}$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
- private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$
- **affine transformation:**  $x_i = \phi_i(z_i) = z_i - \alpha_i, n = 1, \dots, K.$
- **equivalent problem:**

$$\begin{aligned} & \text{minimize} && \sum_{i=1}^K z_i \\ & \text{subject to} && z_i = a_i + \alpha_i, i = 1, \dots, K \end{aligned}$$

- variables are  $z_i \in \mathbb{R}, i = 1, \dots, K$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{array}{ll} \text{minimize} & (1/K) \sum_{i=1}^K x_i \\ \text{subject to} & x_i = a_i, i = 1, \dots, K \end{array} \longrightarrow p^*$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
- private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$
- **affine transformation:**  $x_i = \phi_i(z_i) = z_i - \alpha_i, n = 1, \dots, K.$
- **equivalent problem:**

$$\begin{array}{ll} \text{minimize} & \sum_{i=1}^K z_i \\ \text{subject to} & z_i = a_i + \alpha_i, i = 1, \dots, K \end{array}$$

- variables are  $z_i \in \mathbb{R}, i = 1, \dots, K$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{array}{ll} \text{minimize} & (1/K) \sum_{i=1}^K x_i \\ \text{subject to} & x_i = a_i, i = 1, \dots, K \end{array} \longrightarrow p^*$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
- private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$

- **affine transformation:**  $x_i = \phi_i(z_i) = z_i - \alpha_i, n = 1, \dots, K.$

- **equivalent problem:**

$$\begin{array}{ll} \text{minimize} & \sum_{i=1}^K z_i \\ \text{subject to} & z_i = a_i + \alpha_i, i = 1, \dots, K \end{array} \longrightarrow q^*$$

- variables are  $z_i \in \mathbb{R}, i = 1, \dots, K$

# Example of Change of Variables

- **original problem (find average of  $K$  private numbers):**

$$\begin{array}{ll} \text{minimize} & (1/K) \sum_{i=1}^K x_i \\ \text{subject to} & x_i = a_i, i = 1, \dots, K \end{array} \longrightarrow p^*$$

- variables are  $x_i \in \mathbb{R}, i = 1, \dots, K$
- private numbers:  $a_i \in \mathbb{R}, i = 1, \dots, K$

- **affine transformation:**  $x_i = \phi_i(z_i) = z_i - \alpha_i, n = 1, \dots, K.$

- **equivalent problem:**

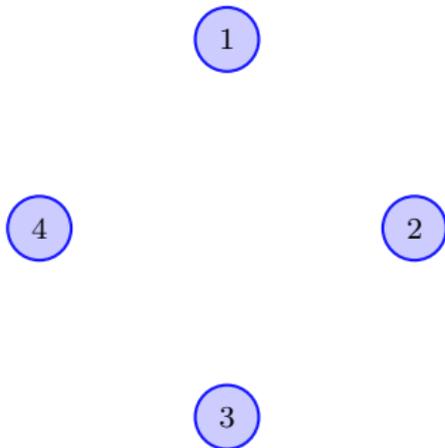
$$\begin{array}{ll} \text{minimize} & \sum_{i=1}^K z_i \\ \text{subject to} & z_i = a_i + \alpha_i, i = 1, \dots, K \end{array} \longrightarrow q^*$$

- variables are  $z_i \in \mathbb{R}, i = 1, \dots, K$

- $p^* = \frac{1}{K} \left( q^* - \sum_{i=1}^K \alpha_i \right)$

# Example of Change of Variables

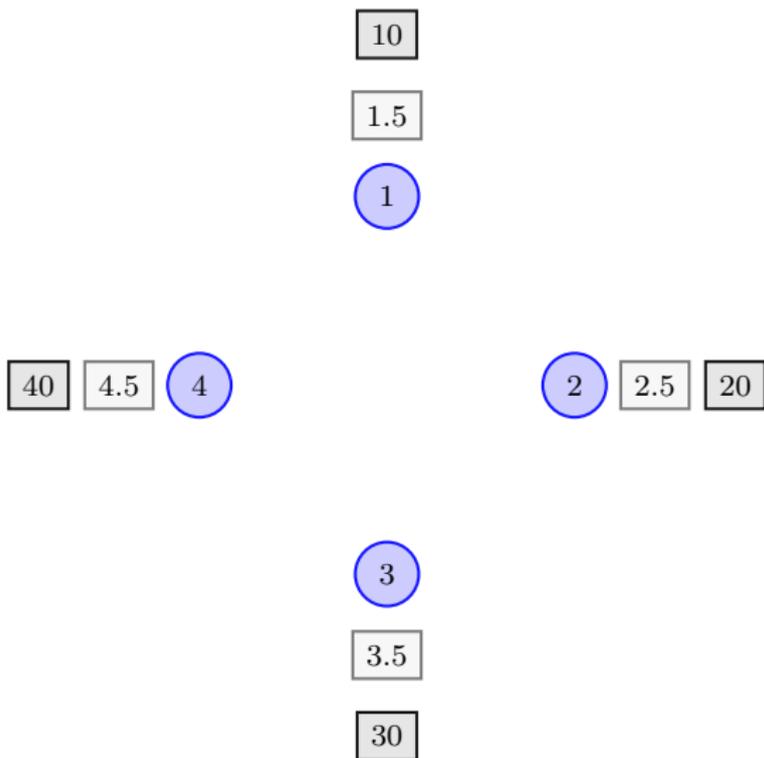
- original problem (find average of  $K$  numbers):





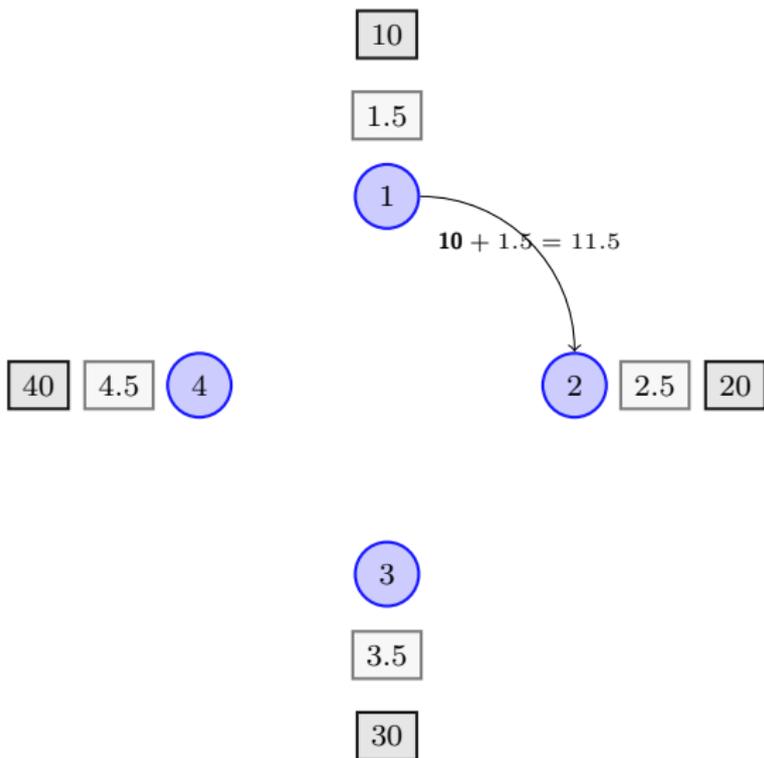
# Example of Change of Variables

- original problem (find average of  $K$  numbers):



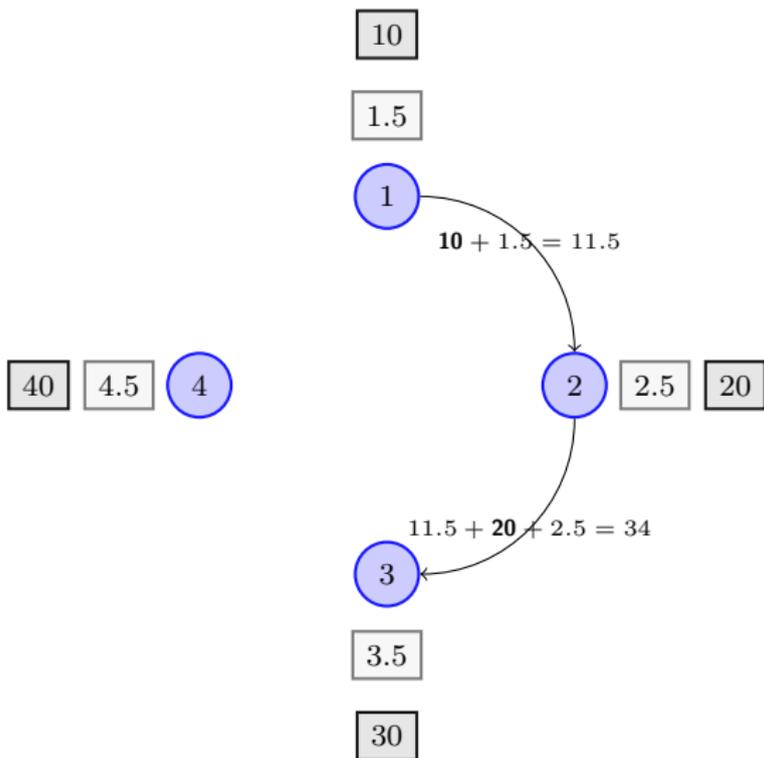
# Example of Change of Variables

- original problem (find average of  $K$  numbers):



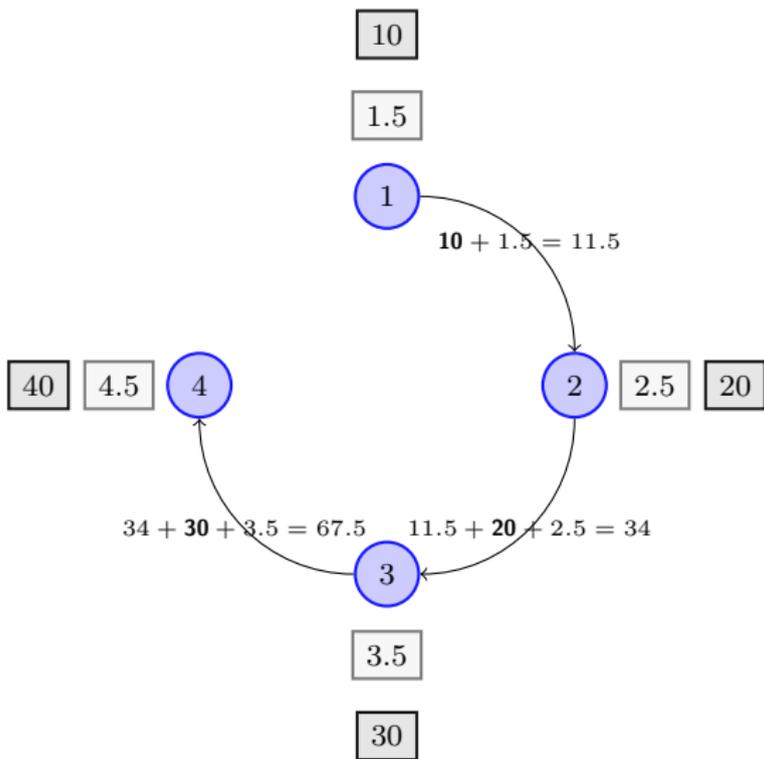
# Example of Change of Variables

- original problem (find average of  $K$  numbers):



# Example of Change of Variables

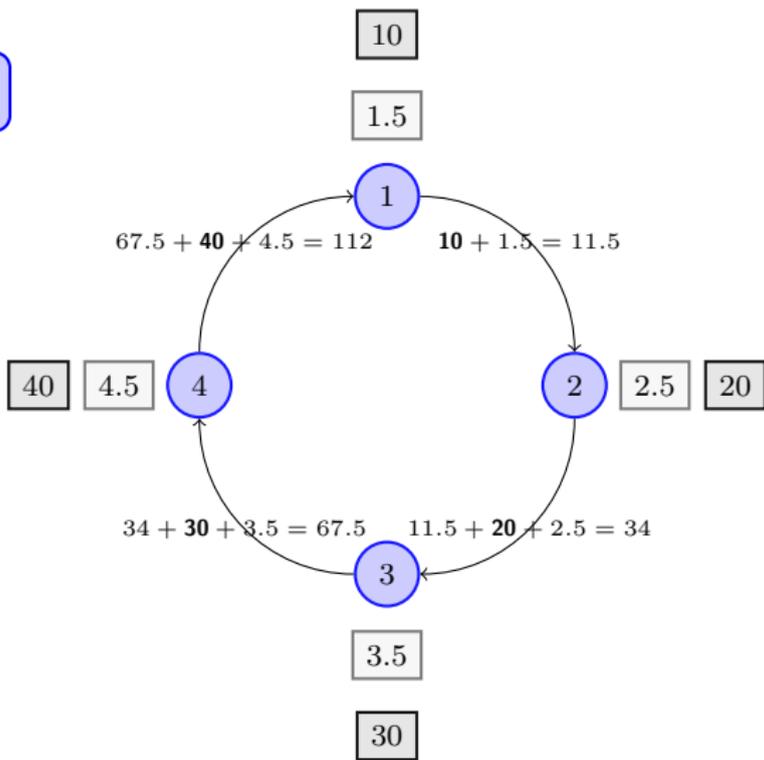
- original problem (find average of  $K$  numbers):



# Example of Change of Variables

- original problem (find average of  $K$  numbers):

$$q^* = 112$$



# Example of Change of Variables

- original problem (find average of  $K$  numbers):

$$q^* = 112$$

10

1.5

1

40 4.5 4

2 2.5 20

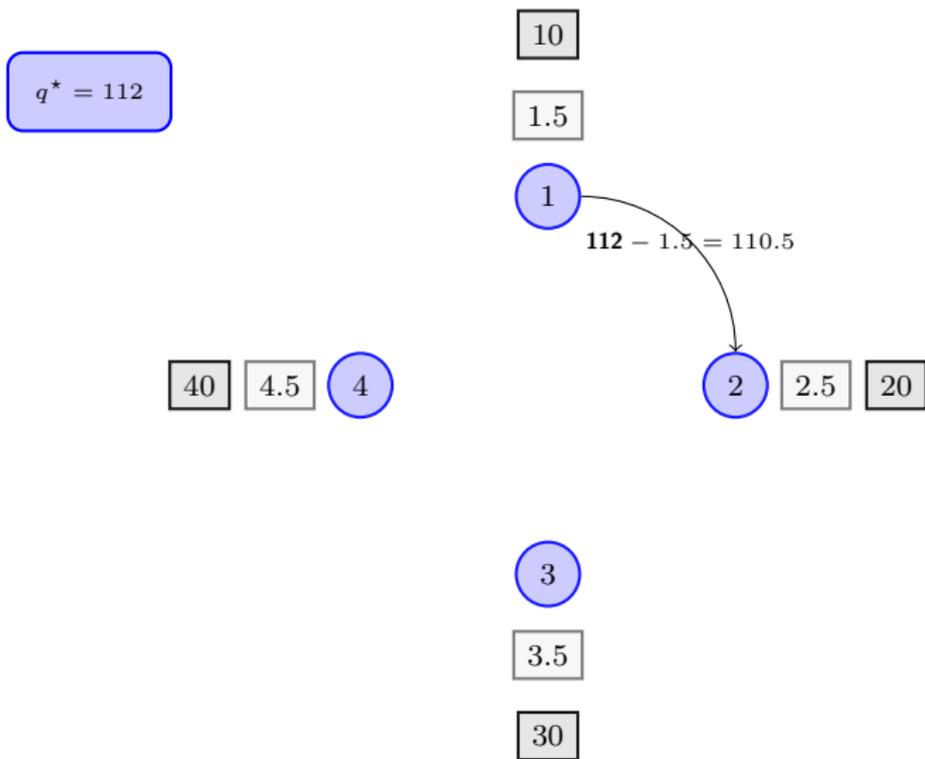
3

3.5

30

# Example of Change of Variables

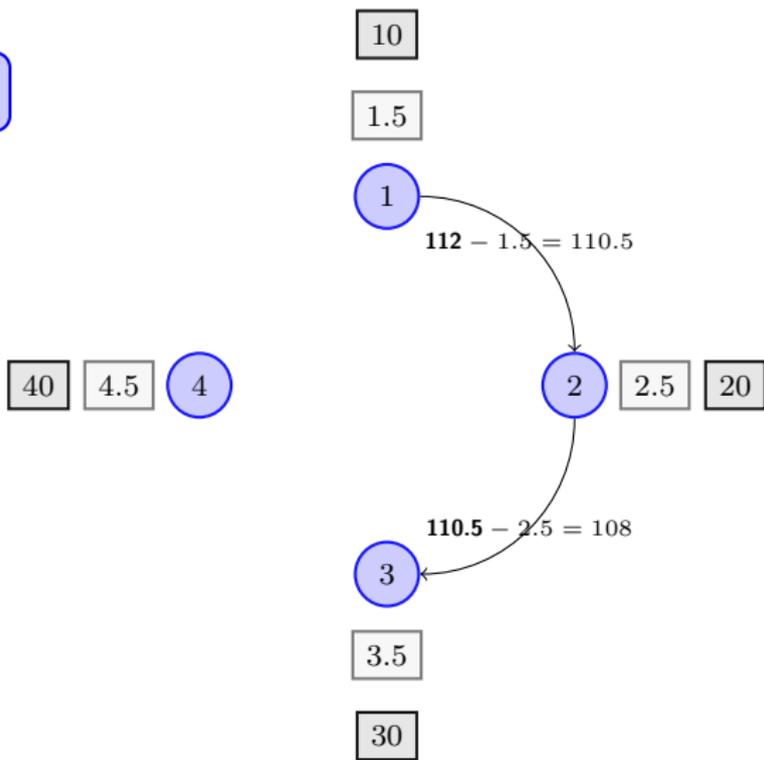
- original problem (find average of  $K$  numbers):



# Example of Change of Variables

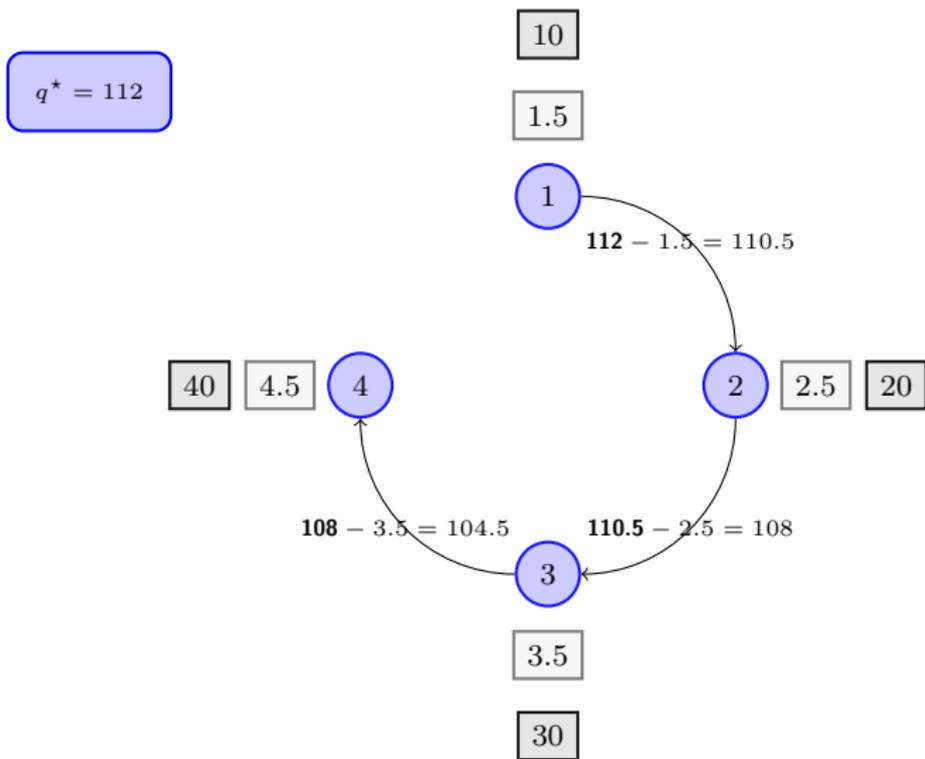
- original problem (find average of  $K$  numbers):

$q^* = 112$



# Example of Change of Variables

- original problem (find average of  $K$  numbers):

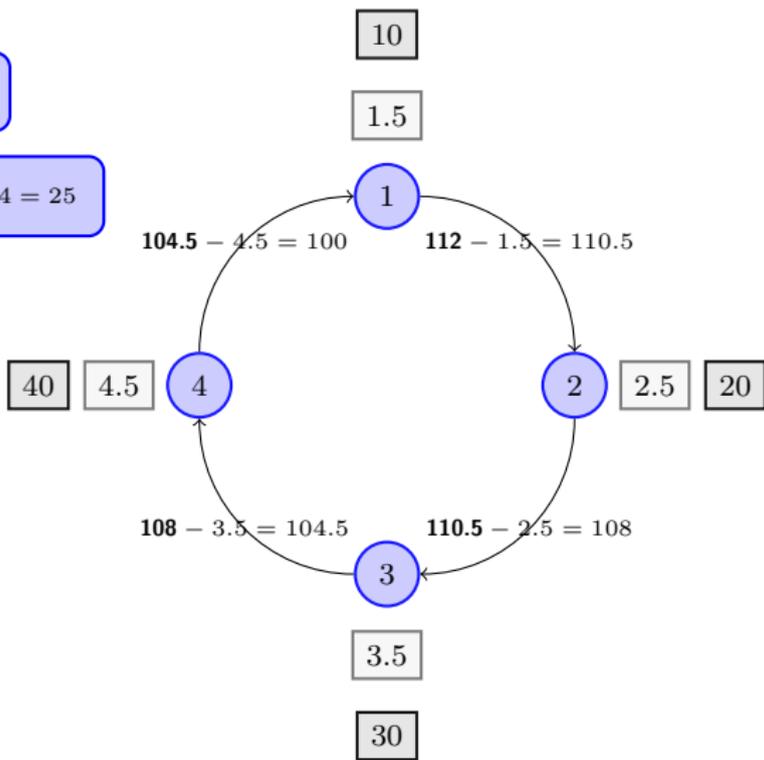


# Example of Change of Variables

- original problem (find average of  $K$  numbers):

$$q^* = 112$$

$$p^* = 100/4 = 25$$



# Unification, Disguising Private Data for SMC

## Proposition (transformation of objective and constraint functions)

- $\psi_0 : \mathbb{D}_0 \subseteq \mathbb{R} \rightarrow \mathbb{R}$  is monotonically increasing and  $\mathbb{D}_0 \supseteq \text{image} f_0$
- $\psi_i : \mathbb{D}_i \subseteq \mathbb{R} \rightarrow \mathbb{R}$ , with  $\mathbb{D}_i \supseteq \text{image} f_i$  and  $\psi_i(z) \leq 0 \Leftrightarrow z \leq 0$
- $\psi : \mathbb{R}^p \rightarrow \mathbb{R}^m$  satisfies  $\psi(\mathbf{z}) = \mathbf{0} \Leftrightarrow \mathbf{z} = \mathbf{0}$
- if  $\mathbf{x}^*$  solves

$$\begin{aligned} & \text{minimize} && \psi_0(f_0(\mathbf{x})) \\ & \text{subject to} && \psi_i(f_i(\mathbf{x})) \leq 0, \quad i = 1, \dots, q \\ & && \psi(\mathbf{C}\mathbf{x} - \mathbf{d}) = \mathbf{0} \end{aligned} \quad (4)$$

then solution  $\mathbf{x}^*$  problem (1)

- the optimal value of problem (1),  $p^*$ , and that of problem (4),  $q^*$ , are related by

$$\psi_0(p^*) = q^* . \quad (5)$$

# Unification, Disguising Private Data for SMC

## Proposition (transformation of objective and constraint functions)

- $\psi_0 : \mathbb{D}_0 \subseteq \mathbb{R} \rightarrow \mathbb{R}$  is monotonically increasing and  $\mathbb{D}_0 \supseteq \text{image} f_0$
- $\psi_i : \mathbb{D}_i \subseteq \mathbb{R} \rightarrow \mathbb{R}$ , with  $\mathbb{D}_i \supseteq \text{image} f_i$  and  $\psi_i(z) \leq 0 \Leftrightarrow z \leq 0$
- $\psi : \mathbb{R}^p \rightarrow \mathbb{R}^m$  satisfies  $\psi(\mathbf{z}) = \mathbf{0} \Leftrightarrow \mathbf{z} = \mathbf{0}$
- if  $\mathbf{x}^*$  solves

$$\begin{aligned} & \text{minimize} && \psi_0(f_0(\mathbf{x})) \\ & \text{subject to} && \psi_i(f_i(\mathbf{x})) \leq 0, \quad i = 1, \dots, q \\ & && \psi(\mathbf{C}\mathbf{x} - \mathbf{d}) = \mathbf{0} \end{aligned} \quad (4)$$

then solution  $\mathbf{x}^*$  problem (1)

- the optimal value of problem (1),  $p^*$ , and that of problem (4),  $q^*$ , are related by

$$\psi_0(p^*) = q^* . \quad (5)$$

privacy is via the function compositions:

$$\bar{f}_i(\mathbf{x}) = \psi_i(f_i(\mathbf{x})) , \quad \text{dom} \bar{f}_i = \{\mathbf{x} \in \text{dom} f_i \mid f_i(\mathbf{x}) \in \text{dom} \psi_i\}$$

$$\bar{h}_i(\mathbf{x}) = \psi(\mathbf{C}\mathbf{x} - \mathbf{d}) \quad \text{dom} \bar{h}_i = \mathbb{R}^n$$

# Example of Transformation of Objective

- **original problem:**

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|_2$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
- private data:  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$
- $\text{rank}(\mathbf{A}) = n$

# Example of Transformation of Objective

- **original problem:**

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|_2$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
  - private data:  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$
  - $\text{rank}(\mathbf{A}) = n$
- $\psi_0(z) = z^2 + b$

# Example of Transformation of Objective

- **original problem:**

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|_2$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
- private data:  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$
- $\text{rank}(\mathbf{A}) = n$

- $\psi_0(z) = z^2 + b$

- **equivalent problem:**

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|_2^2 - \mathbf{b}^\top \mathbf{b} = \mathbf{x}^\top \hat{\mathbf{A}} \mathbf{x} - 2\hat{\mathbf{b}}^\top \mathbf{x}$$

- variable is  $\mathbf{x} \in \mathbb{R}^n$
- data:  $\hat{\mathbf{A}} = \mathbf{A}^\top \mathbf{A} \in \mathbb{R}^{n \times n}$ ,  $\hat{\mathbf{b}} = \mathbf{A}^\top \mathbf{b} \in \mathbb{R}^{n \times 1}$



# Example of Decomposition

- **original problem:**

$$\begin{aligned} & \text{minimize} && \alpha_1 x_1^2 + \alpha_2 x_2^2 \\ & \text{subject to} && \beta_1 x_1 + \beta_2 x_2 = 1 \end{aligned}$$

- variable is  $x_1, x_2 \in \mathbb{R}$

- private data:  $\underbrace{\alpha_1, \beta_1 \in \mathbb{R}}_{\text{party 1}}, \underbrace{\alpha_2, \beta_2 \in \mathbb{R}}_{\text{party 2}}$

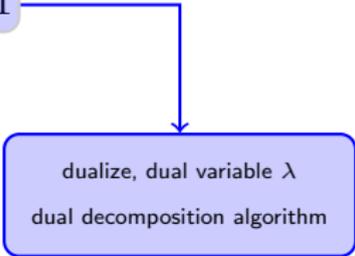
# Example of Decomposition

- original problem:

$$\begin{aligned} &\text{minimize} && \alpha_1 x_1^2 + \alpha_2 x_2^2 \\ &\text{subject to} && \beta_1 x_1 + \beta_2 x_2 = 1 \end{aligned}$$

- variable is  $x_1, x_2 \in \mathbb{R}$

- private data:  $\underbrace{\alpha_1, \beta_1 \in \mathbb{R}}_{\text{party 1}}, \underbrace{\alpha_2, \beta_2 \in \mathbb{R}}_{\text{party 2}}$



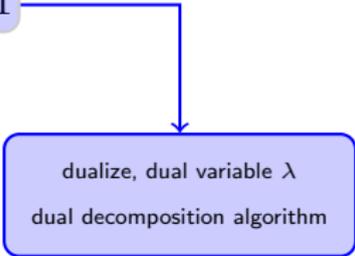
# Example of Decomposition

- original problem:

$$\begin{aligned} & \text{minimize} && \alpha_1 x_1^2 + \alpha_2 x_2^2 \\ & \text{subject to} && \beta_1 x_1 + \beta_2 x_2 = 1 \end{aligned}$$

- variable is  $x_1, x_2 \in \mathbb{R}$

- private data:  $\underbrace{\alpha_1, \beta_1}_{\text{party 1}} \in \mathbb{R}, \underbrace{\alpha_2, \beta_2}_{\text{party 2}} \in \mathbb{R}$



- $k$ th subproblem solved by entity  $i$ :

$$\text{minimize } \alpha_i x_i^2 + \lambda^{(k)} \beta_i x_i$$

- variable is  $x_i \in \mathbb{R}$

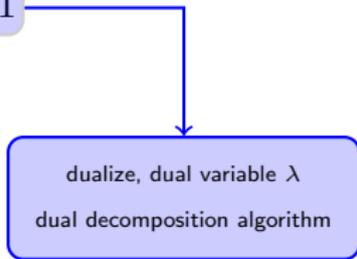
# Example of Decomposition

- original problem:**

$$\begin{aligned} & \text{minimize} && \alpha_1 x_1^2 + \alpha_2 x_2^2 \\ & \text{subject to} && \beta_1 x_1 + \beta_2 x_2 = 1 \end{aligned}$$

- variable is  $x_1, x_2 \in \mathbb{R}$

- private data:  $\underbrace{\alpha_1, \beta_1 \in \mathbb{R}}_{\text{party 1}}, \underbrace{\alpha_2, \beta_2 \in \mathbb{R}}_{\text{party 2}}$



- $k$ th subproblem solved by entity  $i$ :**

$$\text{minimize } \alpha_i x_i^2 + \lambda^{(k)} \beta_i x_i$$

- variable is  $x_i \in \mathbb{R}$

- dual variable update at each entity  $i$ :**

$$\lambda^{(k+1)} = \lambda^{(k)} - (1/k) \left( \underbrace{\beta_1 x_1^{(k)}}_{-\lambda^{(k)} \beta_1^2 / \alpha_1} + \underbrace{\beta_2 x_2^{(k)}}_{-\lambda^{(k)} \beta_2^2 / \alpha_2} - 1 \right)$$

# QUANTIFY PRIVACY

# Quantify Privacy

## Definition (Attacker model, Passive adversary)

- an entity involved in solving the global problem
- does not deviate from the intended protocol
- it obtain messages exchanged during different stages of the solution method
- keeps a record of all information it receives
- try to learn and to discover others' private data

# Quantify Privacy

## Definition (Attacker model, Passive adversary)

- an entity involved in solving the global problem
- does not deviate from the intended protocol
- it obtain messages exchanged during different stages of the solution method
- keeps a record of all information it receives
- try to learn and to discover others' private data

## Definition (Adversarial knowledge)

- the set  $\mathcal{K}$  of information that an adversary might exploit to discover private data
- set  $\mathcal{K}$  can encompass
  - *real-valued components*:  $\mathcal{K}_{\text{real}}$
  - transformed variants of private data
  - statements

# Quantify Privacy

Definition (Privacy index,  $(\xi, \eta) \in [0, 1) \times \mathbb{N}$ )

- private data  $c \in \mathcal{C}$  is related to some adversarial knowledge  $\mathbf{k} \in \mathcal{K}_{\text{real}} \subseteq \mathcal{K}$  by a vector values function  $f_c : \mathcal{C} \times \mathcal{K}_{\text{real}} \rightarrow \mathbb{R}^m$ , such that  $f_c(c, \mathbf{k}) \leq \mathbf{0}$
- consider the uncertainty set

$$\mathcal{U} = \{c \mid f_c(c, \mathbf{k}) \leq \mathbf{0}, f_c \text{ is arbitrary, } \mathcal{K}\} \quad (6)$$

- then

$$\xi = 1 - 1/N_{\mathcal{K}}, \quad N_{\mathcal{K}} \text{ is the cardinality of } \mathcal{U} \quad (7)$$

$$\eta = \text{affine dimension of } \mathcal{U} \quad (8)$$

# Quantify Privacy

Definition (Privacy index,  $(\xi, \eta) \in [0, 1) \times \mathbb{N}$ )

- private data  $c \in \mathcal{C}$  is related to some adversarial knowledge  $\mathbf{k} \in \mathcal{K}_{\text{real}} \subseteq \mathcal{K}$  by a vector values function  $f_c : \mathcal{C} \times \mathcal{K}_{\text{real}} \rightarrow \mathbb{R}^m$ , such that  $f_c(c, \mathbf{k}) \leq \mathbf{0}$
- consider the uncertainty set

$$\mathcal{U} = \{c \mid f_c(c, \mathbf{k}) \leq \mathbf{0}, f_c \text{ is arbitrary, } \mathcal{K}\} \quad (6)$$

- then

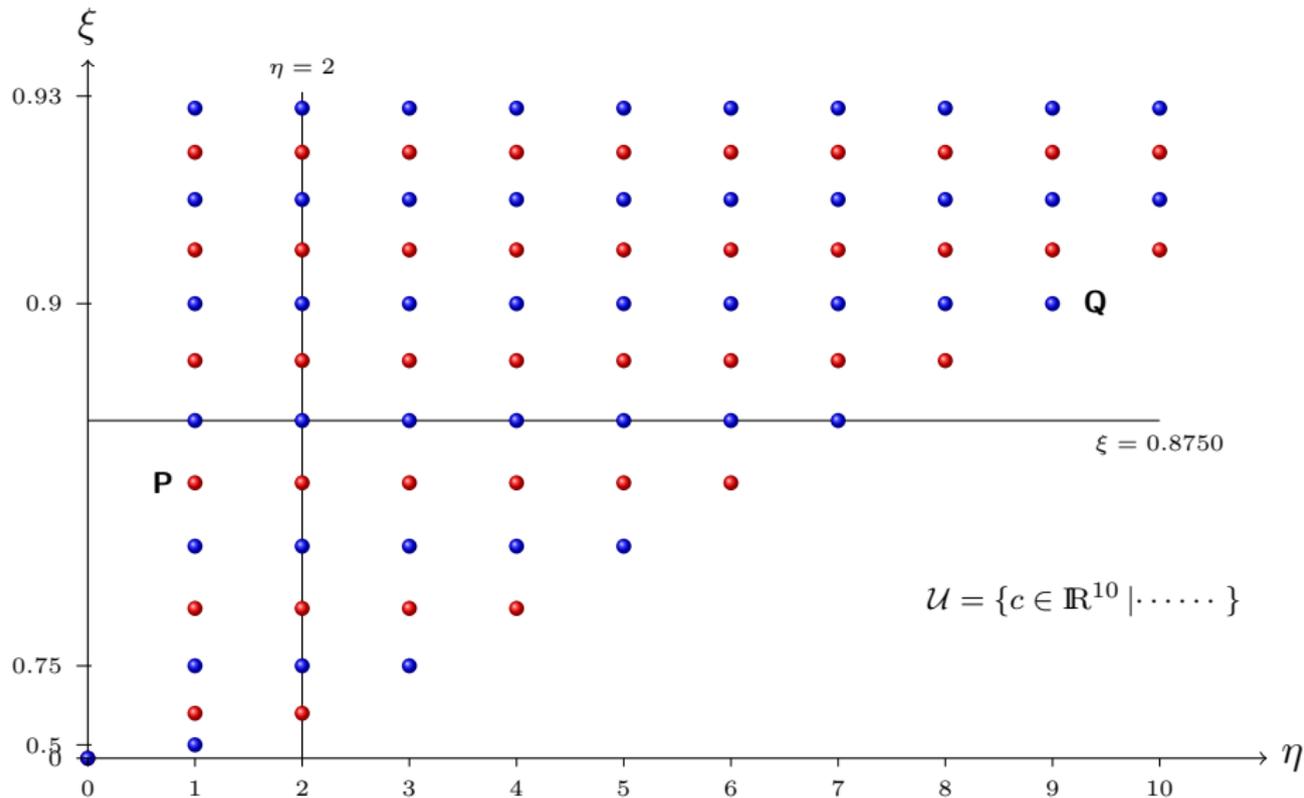
$$\xi = 1 - 1/N_{\mathcal{K}}, \quad N_{\mathcal{K}} \text{ is the cardinality of } \mathcal{U} \quad (7)$$

$$\eta = \text{affine dimension of } \mathcal{U} \quad (8)$$

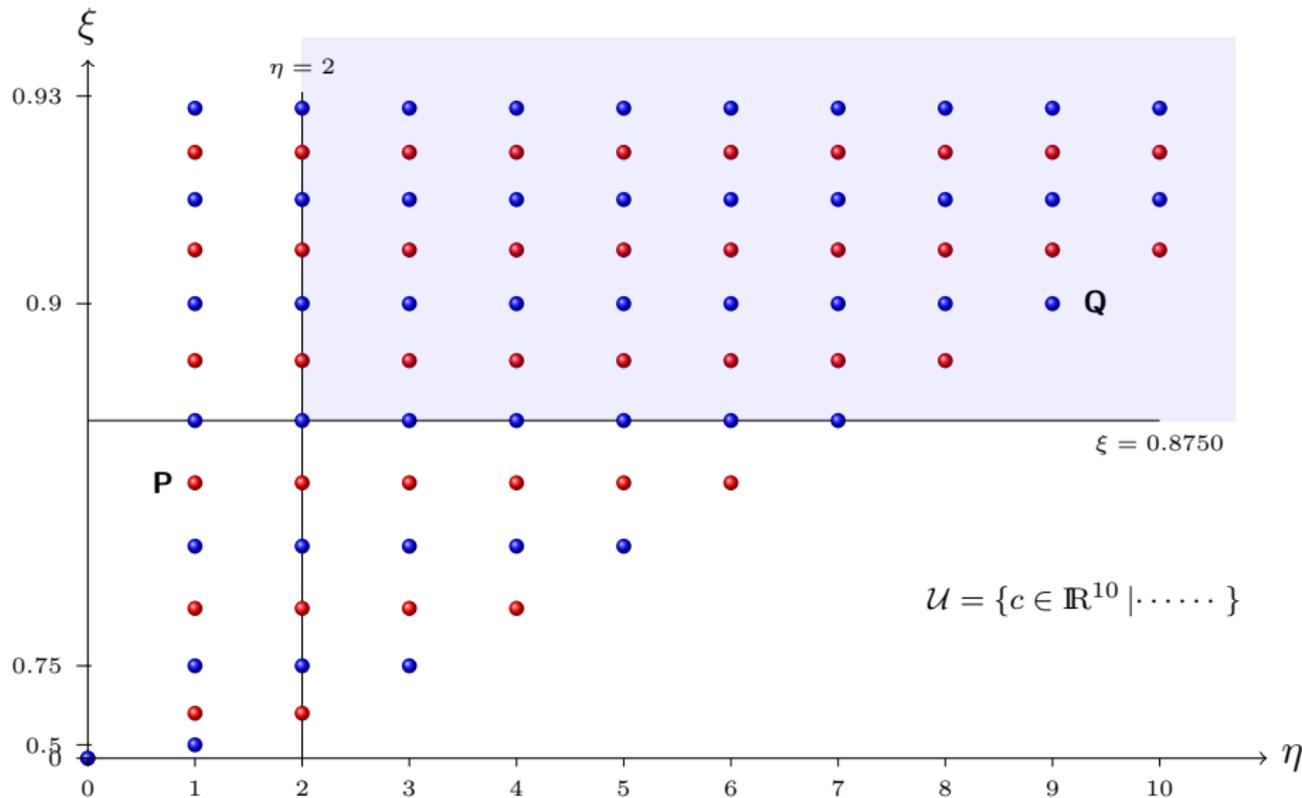
$\xi$  : a measure of probability that the adversary guesses wrong

$\eta$  : indicates how effective the transformation disguises the private data

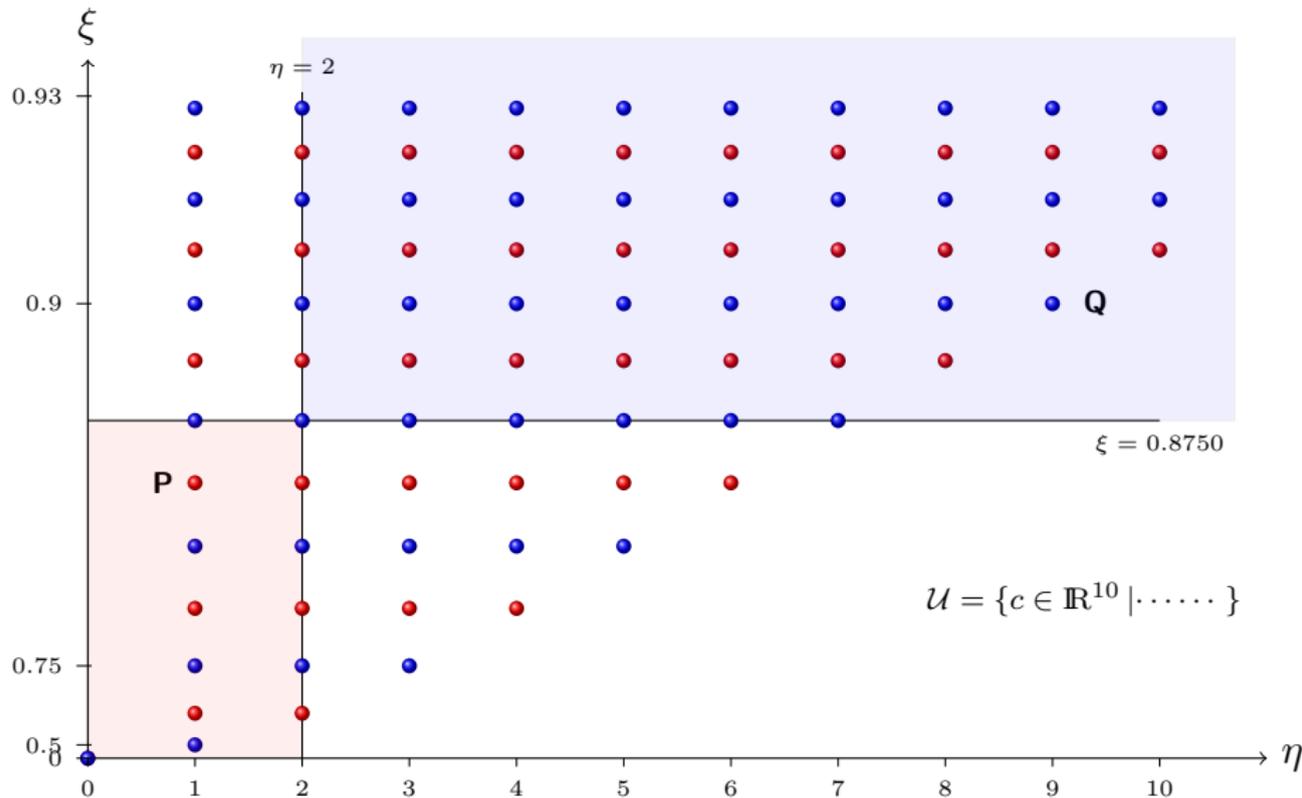
# Quantify Privacy



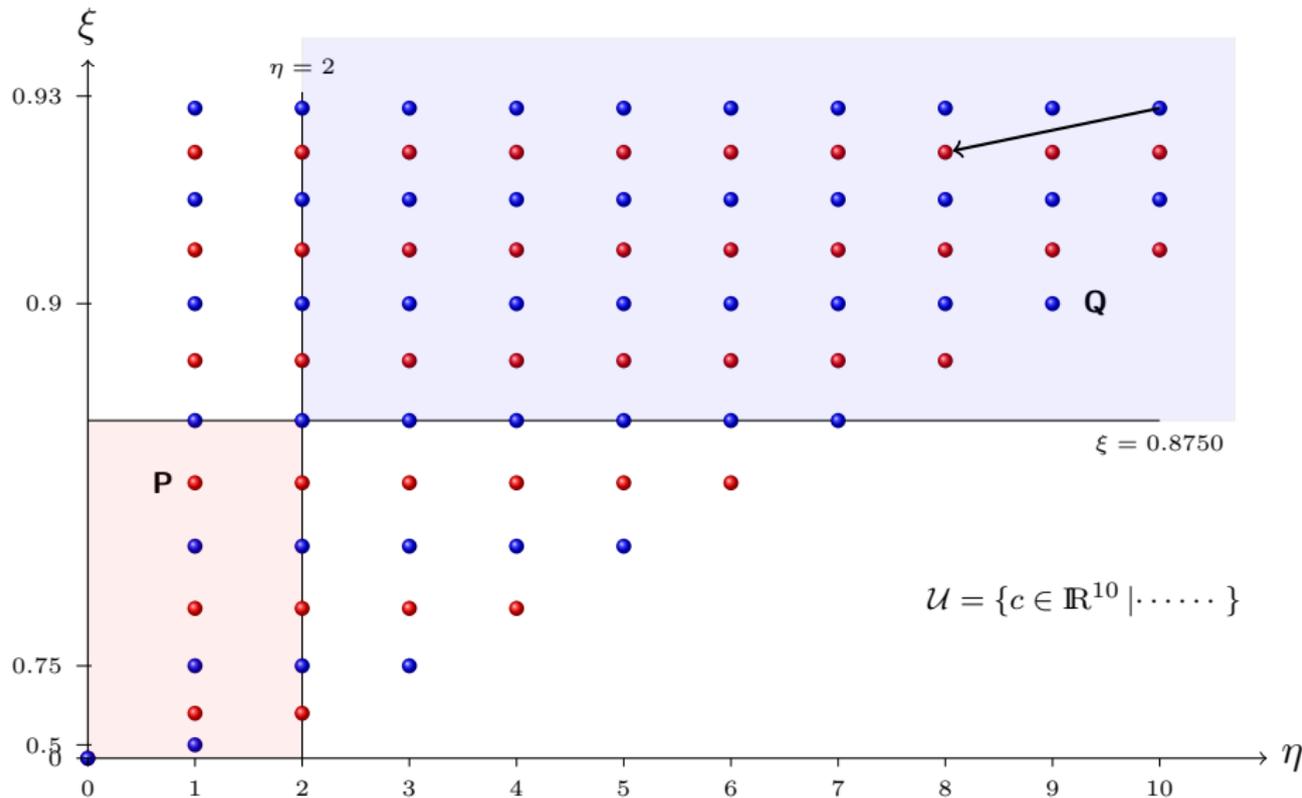
# Quantify Privacy



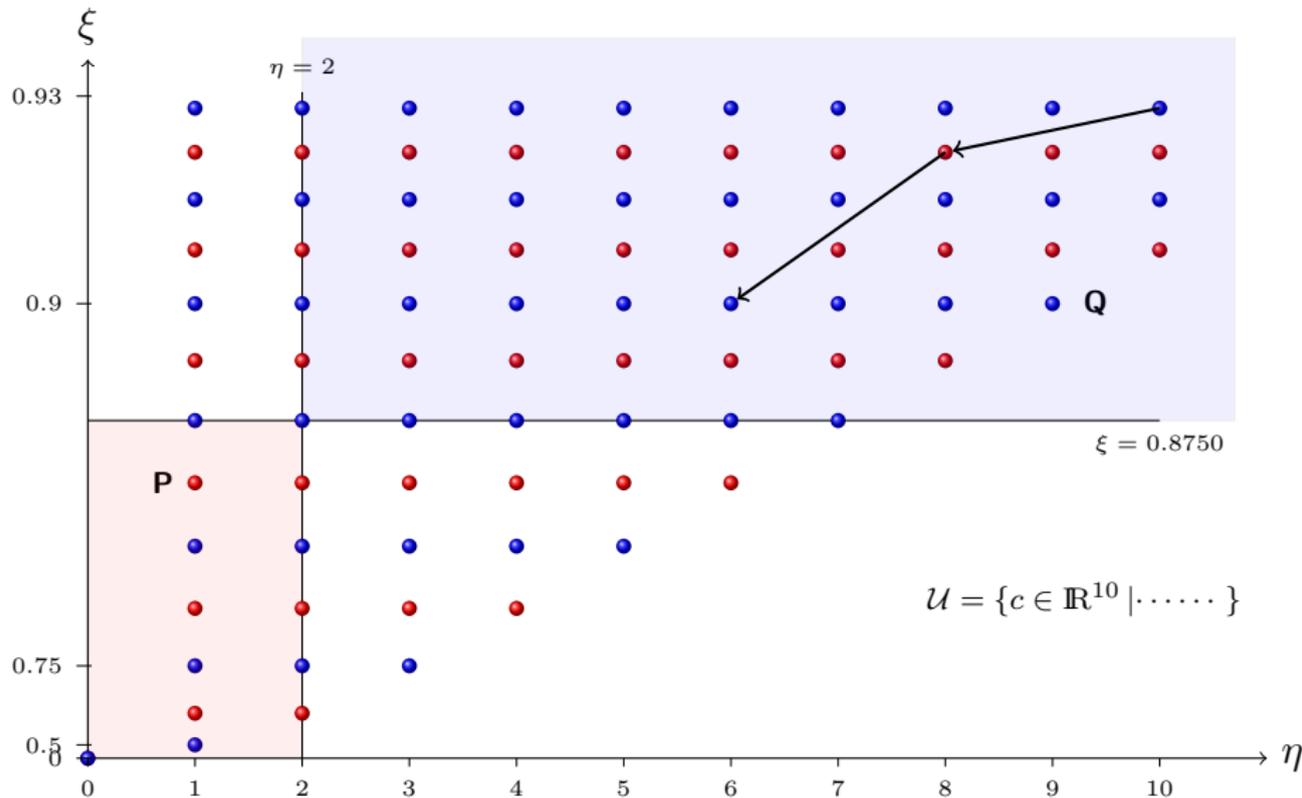
# Quantify Privacy



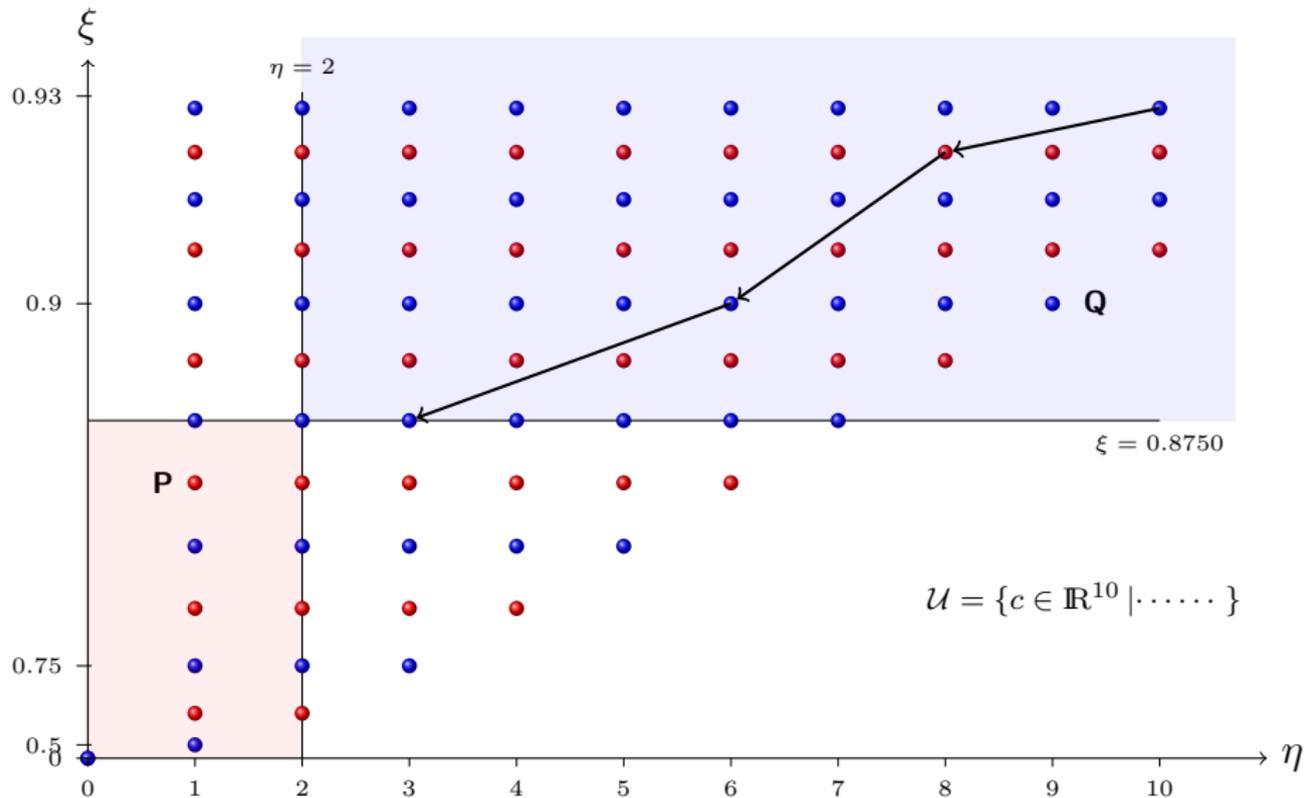
# Quantify Privacy



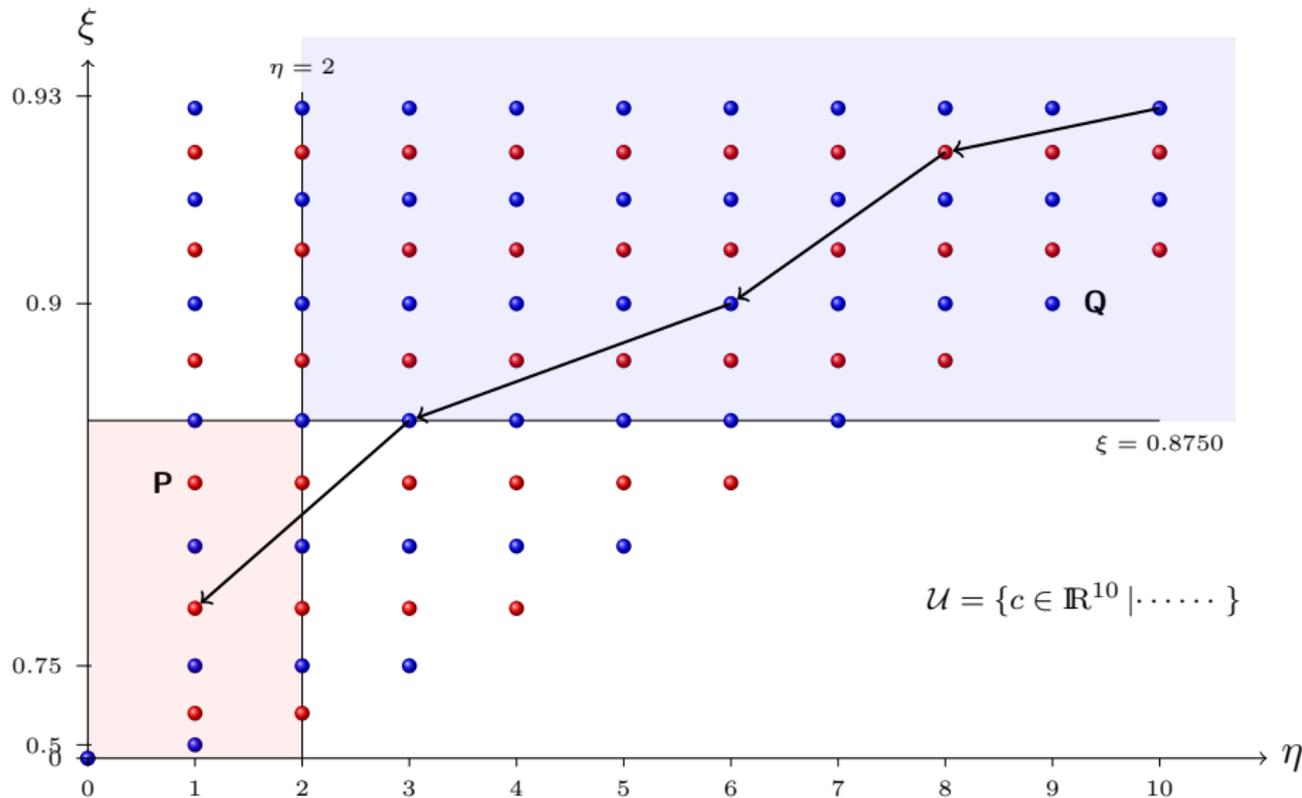
# Quantify Privacy



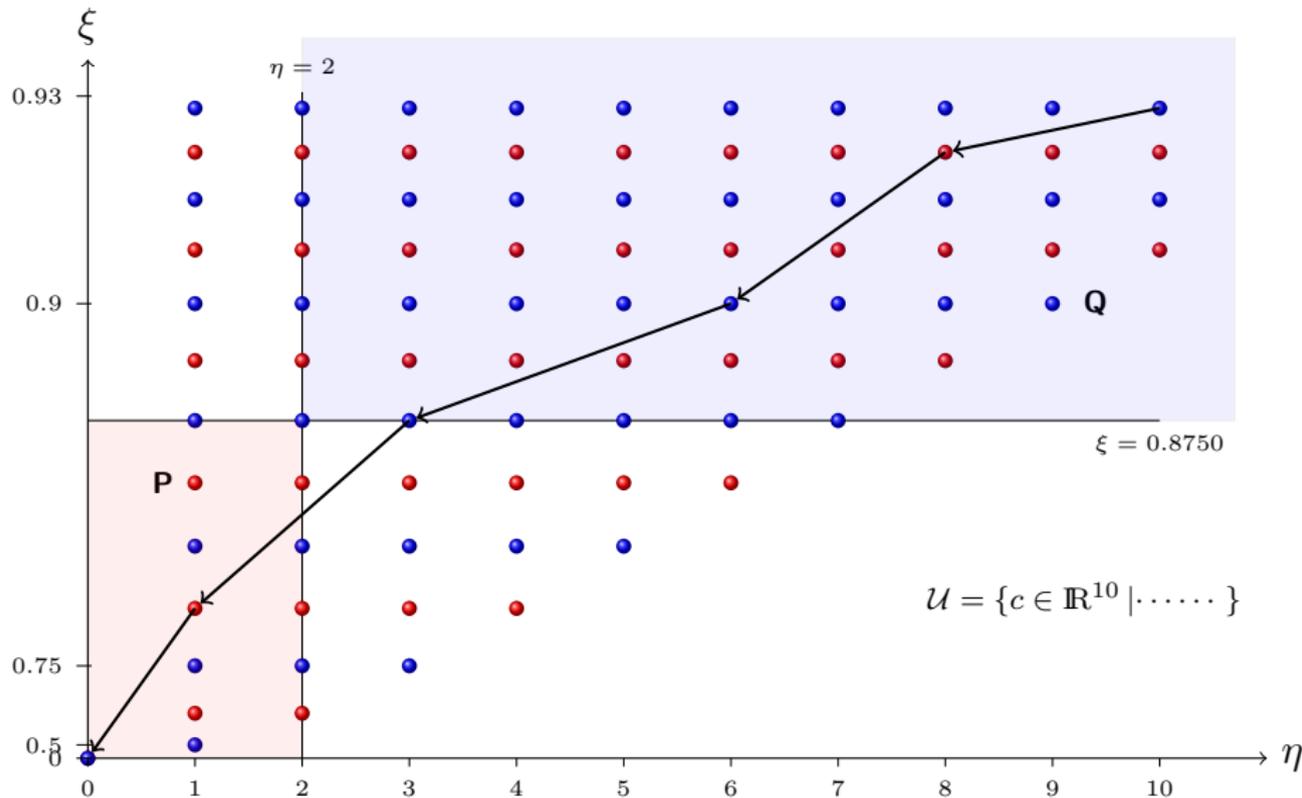
# Quantify Privacy



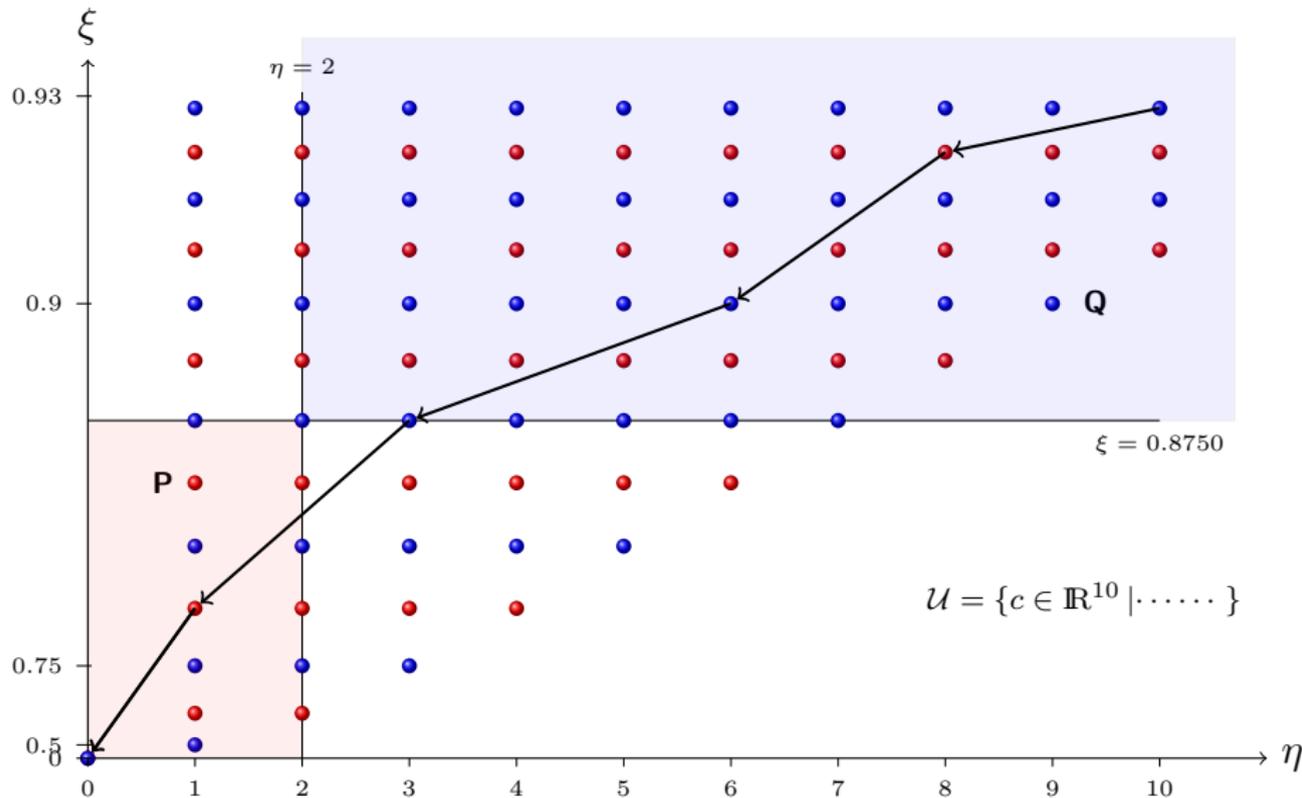
# Quantify Privacy



# Quantify Privacy



# Quantify Privacy



# Privacy Index in a Least-Squares Problem

- **original problem:**

$$\text{minimize } \| \mathbf{a}x - \mathbf{b} \|_2$$

- variable is  $x \in \mathbb{R}$
- private data:  $\mathbf{a} = (\mathbf{a}_1, \mathbf{a}_2) \in \mathbb{R}^6$ ,  $\mathbf{b} = (\mathbf{b}_1, \mathbf{b}_2) \in \mathbb{R}^6$
- 2-parties: party 1 owns  $\mathbf{a}_1, \mathbf{b}_1$ , party 2 owns  $\mathbf{a}_2, \mathbf{b}_2$

- **equivalent problem:**

$$\text{minimize } \| \mathbf{a}x - \mathbf{b} \|_2^2 - \mathbf{b}^\top \mathbf{b} = (r_1 + r_2)x^2 - 2(s_1 + s_2)x$$

- variable is  $x \in \mathbb{R}$
- data:  $r_i = \mathbf{a}_i^\top \mathbf{a}_i$ ,  $i = 1, 2$ ;  $s_i = \mathbf{a}_i^\top \mathbf{b}_i$ ,  $i = 1, 2$

# Privacy Index in a Least-Squares Problem

- **original problem:**

$$\text{minimize } \| \mathbf{a}x - \mathbf{b} \|_2$$

- variable is  $x \in \mathbb{R}$
- private data:  $\mathbf{a} = (\mathbf{a}_1, \mathbf{a}_2) \in \mathbb{R}^6$ ,  $\mathbf{b} = (\mathbf{b}_1, \mathbf{b}_2) \in \mathbb{R}^6$
- 2-parties: party 1 owns  $\mathbf{a}_1, \mathbf{b}_1$ , party 2 owns  $\mathbf{a}_2, \mathbf{b}_2$

- **equivalent problem:**

$$\text{minimize } \| \mathbf{a}x - \mathbf{b} \|_2^2 - \mathbf{b}^\top \mathbf{b} = (r_1 + r_2)x^2 - 2(s_1 + s_2)x$$

- variable is  $x \in \mathbb{R}$
- data:  $r_i = \mathbf{a}_i^\top \mathbf{a}_i$ ,  $i = 1, 2$ ;  $s_i = \mathbf{a}_i^\top \mathbf{b}_i$ ,  $i = 1, 2$

# Privacy Index in a Least-Squares Problem

- party 2 is the adversary and wants to discover  $\mathbf{a}_1$
- knowledge of party 2

$$\mathcal{K} = \left\{ r_1, s_1, \{r_1 = \mathbf{a}_1^\top \mathbf{a}_1\}, \{s_1 = \mathbf{b}_1^\top \mathbf{a}_1\} \right\}$$

- the uncertainty set of  $\mathbf{a}_1$ :

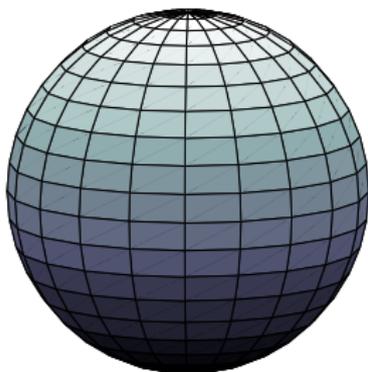
$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^\top \mathbf{a}_1, s_1 = \mathbf{b}_1^\top \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

# Privacy Index in a Least-Squares Problem

- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^\top \mathbf{a}_1, s_1 = \mathbf{b}_1^\top \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

# Privacy Index in a Least-Squares Problem

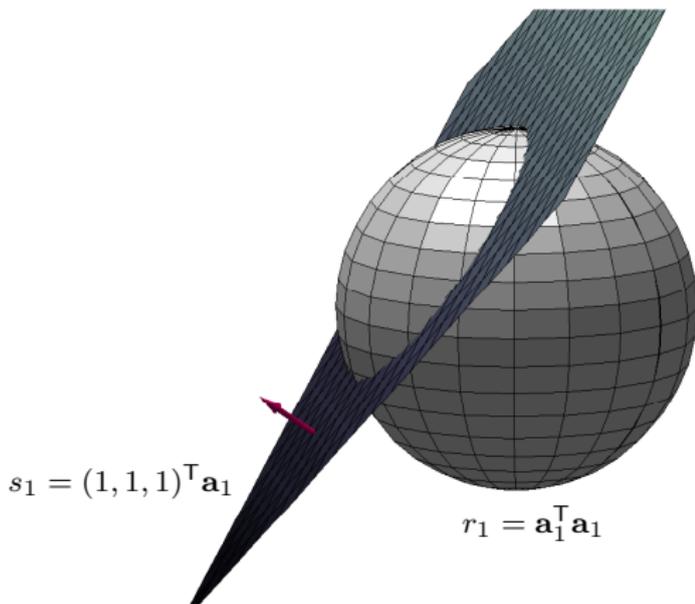


$$r_1 = \mathbf{a}_1^T \mathbf{a}_1$$

- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

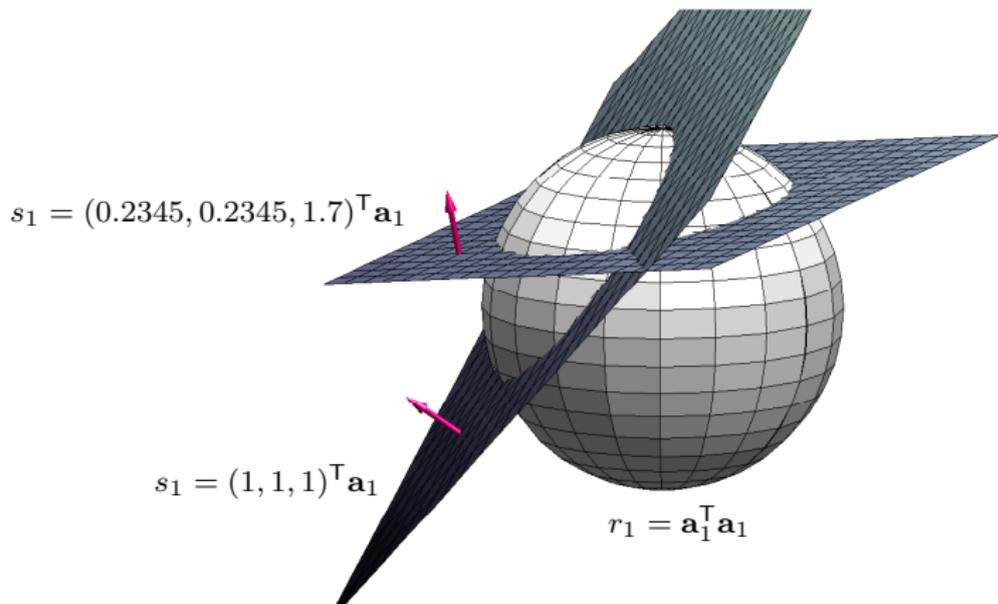
# Privacy Index in a Least-Squares Problem



- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

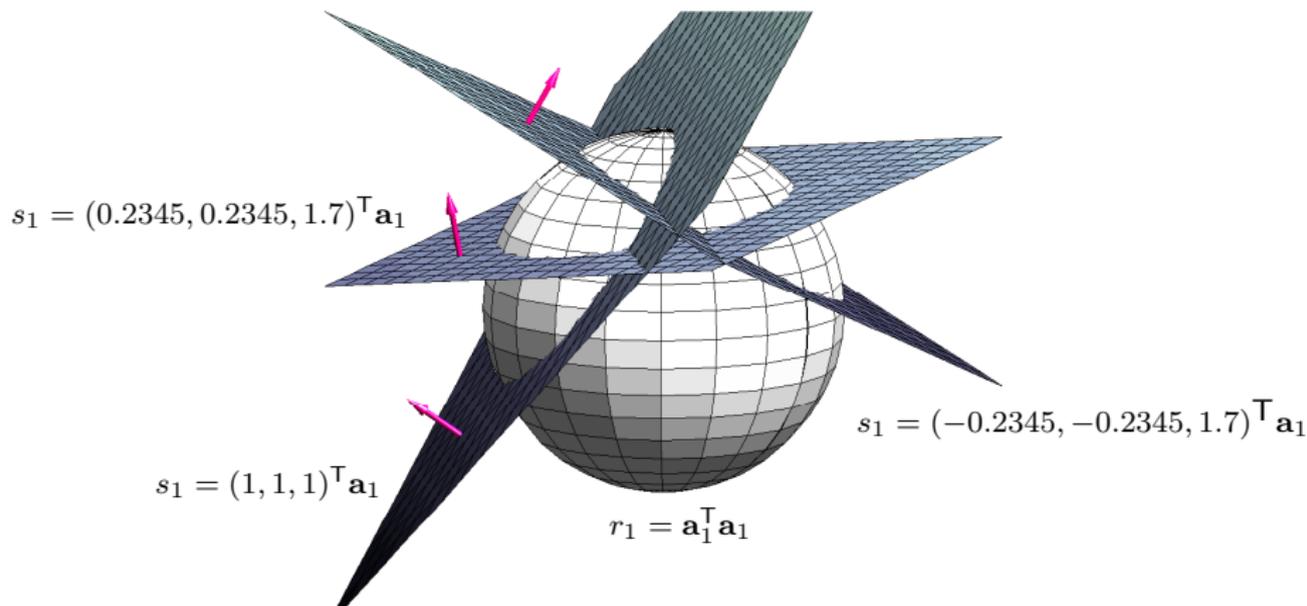
# Privacy Index in a Least-Squares Problem



- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

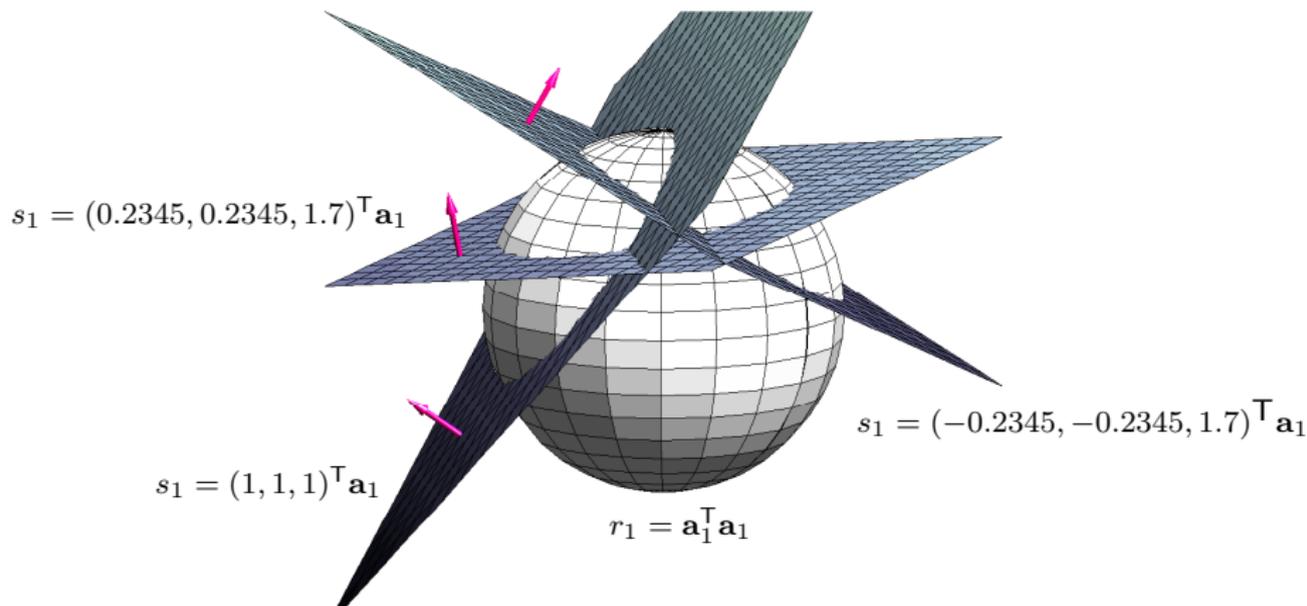
# Privacy Index in a Least-Squares Problem



- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

# Privacy Index in a Least-Squares Problem



$\mathbf{b}_1$  is known:  $(\xi, \eta) = (1, 2)$   
 $\mathbf{b}_1$  is arbitrary:  $(\xi, \eta) = (1, 3)$

CRYPTOGRAPHY  
Vs  
NON-CRYPTOGRAPHIC METHODS

# Cryptographic vs Non-Cryptographic Methods

Cryptographic methods	Non-Cryptographic methods
<ul style="list-style-type: none"> <li>large circuit representations (1000s of bits) to compute <math>f(\mathbf{A}_1, \dots, \mathbf{A}_n)</math></li> </ul>	no such restrictions
<ul style="list-style-type: none"> <li>not scalable</li> </ul>	scalable
<ul style="list-style-type: none"> <li>finite field restriction for <math>\mathbf{A}_i</math></li> </ul>	no such restrictions
<ul style="list-style-type: none"> <li>hardly handle non-integer valued <math>\mathbf{A}_i</math> (overflow, underflow, round-off, and truncations errors)</li> </ul>	no such restrictions HQ implementations (LAPACK,BLAS)
<ul style="list-style-type: none"> <li><math>f_0</math> and <math>\mathbf{g}</math> are often restricted</li> </ul>	no hard restrictions
<ul style="list-style-type: none"> <li>mechanism influences the algorithm iterations</li> </ul>	mechanism is transparent to the solver
<ul style="list-style-type: none"> <li>theory for general <math>f_0</math> and <math>\mathbf{g}</math> are not promising</li> </ul>	there exist a rich and a promising theory, e.g., convex optimization
<ul style="list-style-type: none"> <li>privacy guaranties for <math>\mathbf{A}_i</math> are broadly studied</li> </ul>	to be investigated

# Cryptographic vs Non-Cryptographic Methods

Cryptographic methods	Non-Cryptographic methods
<ul style="list-style-type: none"> <li>large circuit representations (1000s of bits) to compute <math>f(\mathbf{A}_1, \dots, \mathbf{A}_n)</math></li> </ul>	no such restrictions
<ul style="list-style-type: none"> <li>not scalable</li> </ul>	scalable
<ul style="list-style-type: none"> <li>finite field restriction for <math>\mathbf{A}_i</math></li> </ul>	no such restrictions
<ul style="list-style-type: none"> <li>hardly handle non-integer valued <math>\mathbf{A}_i</math> (overflow, underflow, round-off, and truncations errors)</li> </ul>	no such restrictions HQ implementations (LAPACK,BLAS)
<ul style="list-style-type: none"> <li><math>f_0</math> and <math>\mathbf{g}</math> are often restricted</li> </ul>	no hard restrictions
<ul style="list-style-type: none"> <li>mechanism influences the algorithm iterations</li> </ul>	mechanism is transparent to the solver
<ul style="list-style-type: none"> <li>theory for general <math>f_0</math> and <math>\mathbf{g}</math> are not promising</li> </ul>	there exist a rich and a promising theory, e.g., convex optimization
<ul style="list-style-type: none"> <li><b>privacy guaranties for <math>\mathbf{A}_i</math> are broadly studied</b></li> </ul>	<b>to be investigated</b>



# Cryptographic Vs Non-Cryptographic Methods

encrypting simplex algorithm iterations...a quote from Toft [Tof09]

- start with **32-bit numbers**
- **after ten iterations** these have grown to **32 thousand bits**
- **after twenty iterations** they have increased to **32 million**
- even small inputs  $\Rightarrow$  basic operations  $\Rightarrow$  mod. exponentiations with a million bit modulus"

INEFFICIENT

# Conclusions

If you think cryptography is  
the answer to your problem,  
then you dont know what  
your problem is.

-PETER G. NUMANN  
Principal Scientist, SRI International  
Menlo Park, CA, 94025 USA







# ON THE APPLICATION OF OPTIMIZATION METHODS FOR SECURED MULTIPARTY COMPUTATIONS

**C. Weeraddana\***, G. Athanasiou\*, M. Jakobsson\*,  
C. Fischione\*, and J. S. Baras\*\*

\*KTH Royal Institute of Technology, Stockholm, Sweden

\*\*University of Maryland, MD, USA

{chatw, georgia, mjakobss, carlofi}@kth.se; baras@umd.edu

ACCESS ISS 18.09.13

- [Du01] W. Du.  
*A Study of Several Specific Secure Two-Party Computation Problems.*  
PhD thesis, Purdue University, 2001.
- [Tof09] T. Toft.  
Solving linear programs using multiparty computation.  
*Financ. Crypt. and Data Sec. LNCS*, pages 90–107, 2009.
- [Vai09] J. Vaidya.  
Privacy-preserving linear programming.  
In *Proc. ACM Symp. on App. Comp.*, pages 2002–2007, Honolulu, Hawaii,  
USA, March 2009.
- [WAJ<sup>+</sup>13] P. C. Weeraddana, G. Athanasiou, M. Jakobsson, C. Fischione, and J. S.  
Baras.  
Per-se privacy preserving distributed optimization.  
*arXiv, Cornell University Library*, 2013.  
[Online]. Available: <http://arxiv.org/abs/1210.3283>.